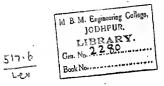
# NOMOGRAPHY

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# NOMOGRAPHY

BY A. S. LEVENS, M.S., C.E.

Professor of Engineering Design University of California, Berkeley, California



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Alexander S. Levens

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#### PREFACE

In science and technology, nomograms are recognized for case of operation and for the time saved in the repeated solution of mathematical formulas. The type of nomogram known as the alignment chart has you much favor during the past two decades. Engineers and scientists teloud be trained sufficiently to understand the mathematical theory and design of nomograms. The material presented in this book is intended to provide a good working knowledge of the fundamental principles.

Emphasis is placed upon the "geometric method" employed in the development of the theory for the design of alignment charts involving quantions of three or more variables. Simple equations are selved by alignment charts consisting of straight-line scales, whereas more involved equations may necessitate the use of "grids," curved scales, and combinations of Cartesian co-ordinate charts with alignment charts.

Once the theory is well understood, practical short-cuts are presented to reduce the time required to design a chart. Examples are given in the chapter "Practical Short-Cuts."

The chapter on the use of determinants serves as an introduction to the 'method of determinants' which has been well developed by such writers as d'Ocagne, Soreau, Hewes and Seward, and Allecck and Jones.

The appendix contains practical examples of alignment charts used in the fields of engineering, production, and statistics.

This book is an autgrowth of nonography courses offered for many years at both the University of Minnesota and the University of California. At present, one-smeater, two-unit, destire courses are open for seniors in expineering, physics, chemistry, business administration, and education. Scientists and practicing engineers will find no difficulty in handling the material in this book, if they have not forpotten the elements of algebra and place geometry and the use of four-rithms.

For those who may develop a keen desire to pursue further study in the fascinating field of Nomography the selected bibliography will provide adequate reference material.

The author is indebted to both Emeritus Professor W. H. Kirchner. formerly head of the Department of Drawing and Descriptive Geometry, and Emeritus Professor W. E. Brooke, formerly head of the Department of Mathematics and Mechanics, at the University of Minnesota, for their guidance and encouragement during the early years of training and experience. Acknowledgments are due undergraduate and graduate students of the author's classes in Nomography, especially Russell M. Carlson, of the Engineering Department, Chance Vought Aircraft Division of United Aircraft Corporation, and colleagues of the Department of Engineering, University of California, for many valuable suggestions. The writer is grateful to Professors B. F. Raber and F. W. Hutchinson of the University of California, authors of "Refrieeration and Air Conditioning Engineering"; the Crane Company: Consolidated Vulter Aircraft Corporation; Crobalt, Inc.: Product Engineering; and Federal Telephone and Radio Corporation for permission to reproduce certain nomograms.

A. B. Levens

Unweresty of California Berkeley, California August, 1947

# CONTENTS

1	Introduction
2	Functional Scales
3	Alignment Charts
4	Alignment Charts (Z Charts) for the Solution of Equations of the Form
	$f_1(u) = f_2(v) \cdot f_3(w) \cdot \dots \cdot \dots \cdot \dots \cdot \dots \cdot \dots$
5	Other Forms of Equations Which Can Be Solved by a $Z$ Caux
	$f_1(u) + f_2(v) = \frac{f_1(u)}{f_3(w)}$
6	Alignment Charts for the Solution of Equations of the Form
	$\frac{1}{f_1(u)} + \frac{1}{f_2(u)} = \frac{1}{f_2(u)} \qquad \qquad \overline{\pi}_{C}$
7	Alignment Charts for Equations of For a line of the Form
	$f_1(u) + f_2(v) + f_3(w) \cdots = \sum_{n=1}^{\infty} \dots $
8	Proportional Charts of the Form
	$\frac{f_1(u)}{f_2(v)} = \frac{f_1(v)}{f_1(v)}  \cdots  \overline{v}$
9	Proportional Charts of the Fe-
	$f_1(a) + f_2(b) = \frac{\sum_{i=1}^{n} a_i}{\sum_{i=1}^{n} a_i}$

10	Alignment Charts for the Solution of Equations of the Form					
	$f_1(u) + f_2(v) \cdot f_3(w) - f_4(w) \cdot \cdot \cdot \cdot \cdot$	99				
11	Miscellaneous Forms	104				
12	Practical Short-Cuts in the Design of Alignment Charts	122				

CONTENTS

126

136

139

173

. . 137

visi

Alignment Charts

Index ...,

Bibliography

Appendix

13 The Use of Determinants in the Design and Construction of

Index to Appendix Augmment Charts . .

### Chapter One

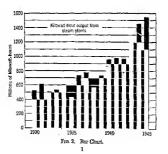
#### INTRODUCTION

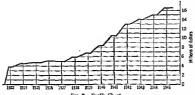
Pictorial representation has proved to be an effective method in conveying technical and semi-technical information to business and professional persons, to production personnel, to

engineers, and to scientists.
Our daily neversions, business magnaines, company publications, technical papers, etc., invariably present graphs and charts which quickly and painlessly discloss information that would otherwise-require lengthy descriptions if presented by the printed word. Figures 1, 2, and 3 are typical of such charts.



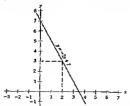
Fig. 1. Ple Chart.





Fro. 3. Profile Chart.

Those engaged in technical work frequently employ the Cartesian co-ordinate system for the representation of the relationship between two or more variables. For example, the straight line y = -2z + 7 is represented graphically by Figure 4. If z = 2, the value of y may be determined by following the arrows shown in the figure. which yields y = 3



Fro. 4. Cartesian Co-ordinate Representation of the Equation, y = -2x + 7. Exquiple: When x = 2, y = 3.

Several equations of the form y = mx + b can, of course, be shown on one set of axes. For example, the equations

$$y = -2x + 1 \tag{1}$$

8

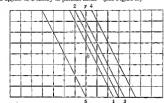
(1)

$$y = -2x + 2$$
 (2)  
 $y = -2x + 3$  (3)

$$y = -2x + 5$$
 (4)

$$y = -2x - 4$$
 (5)

will appear as a family of parallel lines. (See Figure 5.)



Fro. 5. Family of Parallel Lines. (1) y = -2x + 1. (2) y = -2x + 2. (3) y =-2x + 3. (4) y = -2x + 5. (5) y = -2x - 4.

An equation of the form  $f_1(u) + f_2(v) + f_3(w) = f_4(q)$  may be repreresented by a combination of Cartesian co-ordinate charts. For axample, consider the relation u + v + w = q. Let

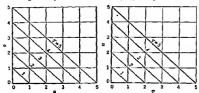
$$u + v = T$$

T + w = aand (2)

Each of these equations is of the form  $f_1(u) + f_2(v) = f_3(w)$  and can

be represented by a family of parallel lines. The first equation, u + v= T, is shown in Figure 6, and the second equation, T + w = q, is of similar form and is represented by Figure 7.

Obviously, not much is gained by solving the given equation, u + v+ w = q, by parts as shown in Figures 6 and 7. A more effective arrangement would make it possible to use values of u, s, and w directly without first determining the value of T. This is quite possible. First, let us analyze what happened in Figures 6 and 7. The equation u + v = T, written in the slope intercept form, would be v = -u + T, showing that for any value of T, we have a line with a negative slope of one and an intercept equal to T. Similarly, the equation T+w=q would be w=-T+q, showing that for any value of q, we have a line with a negative slope of one and an intercept equal to q.



Fro. 6. Cartesian Co-ordinate Representation of the Equation, u+v=T, sentation of the Equation, T+v=T, sentation of the Equation, T+v=g.

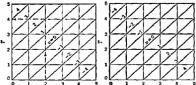


Fig. 8. Cartesian Co-ordinate Representation of the Equation, T=q+n, solution of the Equation, T=q+n, solution for the Equation, T=q-n. Example: When u=2 and v=2; T=4.

Now, suppose we consider equation T = u + v, with T replacing y and u replacing x in the usual equation, y = mx + b. This will result in the graphle representation shown in Figure 8. Similarly, the equation T + w = q may be rewritten as T = q - w. The latter expression is shown graphically in Figure 9.

By combining the two charts as shown in Figure 10 it is now possible to eliminate the graduations of the T scale, and, in fact, the entire T scale, since it is common to both cherts, and read u, v, w, and q directly. This method may be extended further for the solution of equations involving more than four variables.

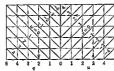


Fig. 10. Combination of Figures 8 and 9 for the Equation, w+v+w=q. Example: When  $w\approx 3, v=1$ , and w=-2; q=2. Follow the arrows shown in chart.

If the given equation is of the form uv = w, logarithmic scales may be employed, thus reducing the equation to  $\log u + \log v = \log w$ . Figure 11 shows the graphic representation of this equation.

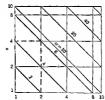


Fig. 11. Cartesian Co-ordinate Representation of the Equation, uv = w. Example: When u = 2 and v = 4; w = 8.

If the equation is of the form uvw = q, a nomegram can be designed as follows:

Let uv = T (1)

and  $Tw \sim q$  (2)

Equations 1 and 2 may be combined, graphically, as shown in Figure 12.

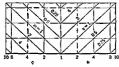
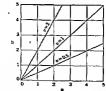


Fig. 12. Cartesian Co-ordinate Representation of the Equation, were =q Example: When w=2, v=4, and w=0.5; q=4.

Legarithmic scales may be eliminated by treating the equation w = v in the following manner. Let y = v and x = v, from which y = vx. This equation represents a pencil of lines passing through the origin with slopes equal to values of v (Figure 13).



Fm. 13. Cartesian Co-ordinate Representation of the Equation,  $uv \rightarrow u$ .

Thus an equation of the form uvw = q may be solved graphically by employing the methods set forth in previous examples.

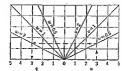


Fig. 14. Cartesian Co-ordinate Representation of the Equation, some = g. Example: When u = 3, v = 0.5, and w = 2, g = 3.

An example of the use of a combination of rectangular Cartesian coordinate charts is shown in Figure 15—"Graph to Determine Engine Rpm."

Another example is presented in Figure 16—"Graphical Evaluation of Heat Storage and Transfer Characteristics, Q' and g',"

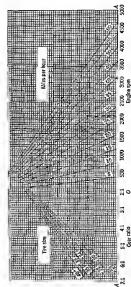
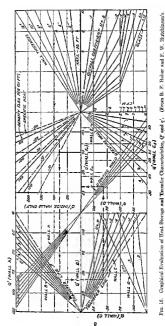


Fig. 15. Graph to Determine Engine Rpm (Courtery of Federal-Megal Corporation, Detroit, Mich.

Based on forwards. Engineerpus (secolarisons per manute) = 25g × R × S



Fell So. Wall C. Sature are Et., bret Q' 34 i Refrigeration and Air Conditioning Buginsering, Wall D. Plata outside: Fin. plaster Curred) Plant: unfinehed surface inside and outside, usive of venour. Durred) Inside. Wall D. renner. Q' is for wall excl.

The simplest type of alignment chart consists of three parallel scales, so graduated that a straight line joining points on two of the scales will cut the third scale at a point that satisfies the relation between the variables. For example, the expression x + y = w can be represented



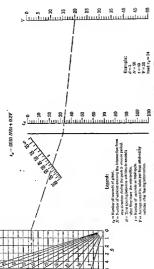
Fig. 17. Alignment Chart for the Equation, x + y = y.

by the alignment chart shown in Figure 17. The line joining x=3 with y=1 cuts the v scale at point 4, which satisfies the equation x+y=v. Similarly, the line joining x=2 with y=4 yields the value v=6.

The simplicity in using alignment charts has wen much favor in technology. They, also, are especially advantageous to neutro-incide personnel, who can employ them with confidence. Alignment charts are used to show the relationship between three, four, five, or more variables. Some of the charts contoin diagonal and curved scales in addition to beforeful and vertical scales. In some cases, it has been found desirable to use a combination of the Cartesian co-ordinate chart and the alignment chart. An example of such a combination is shown in Figure 18—"Nonogram for Deternaining the Number of Seconds of Green Light for Traffic Signals." Various combinations of alignment charts can be developed. The only limitation is the ingenuity of the designer.

The introductory material that has been presented discloses the fact that nonograms may be of the concurrency (Cartesian co-ordinate) type, or of the alignment form, or of a combination of both. The major portion of the material covered in this book deals with the theory and construction of alignment clearts involving straight line sades, curved scales, and combinations of straight line and curved scales. The use of determinants will be demonstrated. However, thorough treatment of the determinant method is not intended since other works which are confined to the "determinants" method only, are available.

Examples of alignment charts which may prove useful in the fields of engineering, production, business, and statistics are included in the Appendix.



## Chapter Two

#### FUNCTIONAL SCALES

The first step necessary in the design of alignment charts is a thorough understanding of the use of functional scales.

A graphical scale is a curved or straight line carrying graduations which correspond to a set of numbers arranged in order of magnitude. If the distances between successive points on the scale are equal for equal increments of the variable, the scale is said to be uniform; if not, the scale is non-uniform

A functional scale is one on which the graduations are marked with the "values of the variable" and on which the distances to the graduations are laid off in proportion to the corresponding values of the "function of the variable". The distances are laid off from an initial point of the scale, not necessaryly the zero point.

#### EXAMPLE

Suppose the function of u, f(u), is  $u^2$  (Figure 19). Let u vary from 0 to 5. Form the following table:

u	0	1	2	3	4	5	_
$f(u) = u^2$	0	1	8	27	61	125	
$z = s^2$	0	1	8	27	64	125	•
0 1	_	, , , , , , , , , , , , , , , , , , ,	±*	-6"	<u>'                                    </u>	_	

We can readily understand that the above scale would be 125 in long if the fuch is used as the unit of measure. Obviously this is not a 01

convenient length. In order to have a scale of a more practical length, a scale modulus or scale multiplier is introduced, that is,  $x = m t^2$  or  $m = x/t^2$ , where m is the scale modulus. The expression x = m f(u) is called the scale equation.

Now suppose that the scale is to be approximately 6 in. long (Figure 20). Then  $m = x/u^2 = 6/125 = 0.048$ . To simplify the computational work, m = 0.05 will be used. This means that the scale length will be 6.25 in, instead of 6 in. The new table then is:

u	0	1	2	3	4	5
$(u) = u^3$	0	1	8	27	64	125
= 0,05u <sup>3</sup>	0	0.05	0.40	1.35	3.20	6.25

Fig. 20. Functional Scale for  $f(u) = u^2$ .

In the practical use of functional scales further subdivision of the scale into fifths or teaths may be advisable. Suppose that the range of the variable is from 2 to 4 and that the scale length is approximately 6 in. (Figure 21). In this case  $z = m[f(u_0) - f(u_1)] = m(4^3 - 2^5) = 56m$  or m = 6/56 = 0.107. For convenience we shall use 0.1. Then we have the table:

	и	2	3	4		
	$f(u) = u^3$	8	27	64	•	
	$x = 0.1(u^3 - 2^2)$	θ	1.9	5.6		
2	3					4

Fig. 21. Functional Scale for f(u) = u<sup>3</sup>.

It should be noted that in this case the initial point of the scale is 2, not 0.

The distance between any two graduations,  $u_1$  and  $u_2$ , is equal to  $x = m[f(u_2) - f(u_1)]$ 

Any unit of length other than inches could be adopted as the unit of measure II is most important to observe (1) that the distance between any two points on the scale is equal to the product of the modulus and the difference in the values of the junction for the two points, not the reluct of the torrighte; and (2) that the points are marked with the value of the variable.

Suppose that the f(u) is  $2u^2$ . The scale equation is  $x = m(2u^3)$ . If u varies from 0 to 4, and the scale length is to be approximately 0 in., then

$$m = \frac{6}{2(4^3)} = \frac{0}{128} = 0.047$$

For convenience, m = 0.05 will be used. This lengthens the scale to 6.4 in.

Hence,  $x = 0.05(2\pi)$  or  $x = 0.1\pi^2$ . It is important to note that 0.1 is the effective modulus, whereas 0.05 is the actual modulus of the scale. The effective modulus is used in graduating the scale. The "scale that occur it amodulus" is necessary in the location of casels atta occur in alignment chart design. This distinction will be evident tater when the design and construction of afferment charts are considered.

If the function of u is (u+2) (Figure 22), then the scale equation is x=m(u+2). If u varies from 0 to 12, and the scale is 6 in long, then

$$m = \frac{6 \ln x}{[(12+2) - (0+2)]} = \frac{6}{12} = \frac{1}{2} \text{ in.}$$

$$x = \frac{5}{2}(x+2)$$

$$0 \quad 1 \quad 2 \quad . \quad 12$$

$$f(x) - (x+2) \quad 2 \quad 3 \quad 4 \quad . \quad 14$$

$$x - \frac{1}{2}(x+2) \quad 1 \quad 15 \quad 2 \quad . \quad 7$$

0 1 2 3 4 5 6 7 8 9 10 11 1

Fro 22. Scale for the Function, (u + 2).

In this case, the constant 2 merely shifts the zero point of the scale a distance from the reference point of the scale equal to  $\frac{1}{2}(0+2) = 1$  in. Except for the shift of the zero point, the scale is that same as though the f(u) were u, because the total length of the scale is  $x = \frac{1}{4} \times 12 = 6$  in., which is the same as  $x = \frac{1}{2}[(12+2) - (0+2)] = 6$  in.

#### EXAMPLE 1

$$f(u) = \sqrt{u}$$

where u varies from 0 to 100, scale length approximately 5 in. (Figure 23).

$$m_u = \frac{6}{\sqrt{100} - \sqrt{0}} = \frac{6}{10}$$

$$x_u = 0.6 \sqrt{u}$$

0 1 2 3 4 5 20 20 30 40 50 60 70 80 90 100

Fra. 23. Functional Scale for  $f(u) = \sqrt{u}$ 

# EXAMPLE 2

$$f(u) = \frac{1}{u^2}$$

where u varies from 1 to 3, scale length 6 in. (Figure 24).

$$\dot{m}_{\rm u} = \frac{6}{\left[\frac{1}{1^2} - \frac{1}{8^2}\right]} = 6.75; \quad x_{\rm u} = 6.75 \left[\frac{1}{u^2} - \frac{1}{1^2}\right]$$

t t	ı	2	8
$f(u) = \frac{1}{u^2}$	1	1	ş
$z_{w} = 6.75 \left[ \frac{1}{u^{2}} - \frac{1}{1^{2}} \right]$	0	-#1 16	-6

Note that the negative distances,  $x_n$ , are laid off to the left of point 1, since distances laid off to the right have been regarded as positive.



Fig 24 Functional Scale for f(u) = 1/u2.

# EXAMPLE 3

$$f(u) = \log u$$

where u varies from 2 to 10, scale length, 7 in. (Figure 25).

$$m_{\nu} = \frac{7}{\log 10 - \log 2} = \frac{7}{\log 5} = 10$$

$$\sigma_{\nu} = 10(\log u - \log 2)$$

A few points are tabulated below:

u	2	1	8	10
logu	0 301	0 600	o ons	1 500
$x_u = 10(\log u - \log 2)$	0	3 01	6 03	6.09

		/(u)·	= log m					
2	3	4	5	6	7	8	9	10
							L	
	Fra. 25	Functional	Scale for t	f(n) m le	er u			

# Suggestions for Drawing Scales:

- (1) Make the shortest strokes -1 in
- (2) Make the intermediate strokes and in.
  - (3) Make the longest strokes 3 in
  - (4) Adjacent strokes should be not less than \(\frac{1}{20}\) in apart, or more than \(\frac{1}{4}\) in.

- (5) The distance between labeled strokes should be not less than 1 in
- (6) The interval between units should be divided into fifths or tenths, if necessary.

# Suggestions for Graphic Precision:

- (1) Layout lines should be sharp and light,
- (2) Finish lines should be sharp and dark.
- (3) Use as large a scale as possible.
- (4) If the chart is to be reduced, use a reducing glass to determine the relative weights of lines required in the original drawing,

#### EXERCISES

#### Functional Scales

- 1. Construct a scale for the function  $f(u) = \sqrt[3]{u}$ . u varies from 0 to 8. Scale length about 6 in.
- Construct a scale for the function f(u) = 2 log u. u varies from 10 to 300. Scale length about 6 in.
  - Construct a scale for the function f(u) = cos u. u varies from 0° to 90°.
- Scale length 6 in. 4. Change the range of the variable of problem 3 to 0° to 180° and construct
- a scale of the same modulus. Construct scales for the functions f(u) = log 1/u, log u, log u<sup>2</sup>, log u<sup>3</sup>. u varies from 1 to 10. Scale length about 6 in. Write the scale equations for
- pach case. Construct a scale for the function f(n) = 1/u, u varies from d to ∞.
- Scale length about 7 in. Where would be the point, n = 0? 7. Construct a scale for the function f(u) = u35. Range of the variable 0 to 10. Scale length about 6 in.
- On one side of a line construct a scale for u<sup>2</sup>, on the other side u<sup>2</sup> + 3. Use the same reference point and same modulus. Range 1 to 5. Do the same for  $\log u$  and  $\log (u + 2)$ . Scale lengths about 6 in.
- 9. Explain the effect of the constant K on the scales in the following scale conations:

$$x_u = mKu$$
 (1)

$$x_{\pi} = m(u + K) \qquad (2)$$

$$x_u = m \log u^K$$
(3)

$$x_u = m \log (u + K) \tag{4}$$

f(t) is the vapor pressure in air corresponding to t, the air temperature, in degrees Fahrenheit:

	10		1(4)	
0	0 0383	55	0.432	
5	0.0491	60	0.517	
10	0.0631	65	0 616	
15	0.0810	70	0.732	
20	0.1026	75	0 866	
25	0.130	80	1.022	
30	0.184	85	1.201	
35	0.203	90	1 408	
40	9.237	95	1.645	
45	0.006	100	1 016	

II. Given the following experimental data:

14	f(u)	14	f(u)
0	0 05	26	0 12
11	0.065	32	0.17
18	0.085	40	0.83

Draw a smooth curve through the points and construct a functional scale for f(u) from the curve.

12. Construct a scale for the wave length of the various colors of hight: Wave Length

Colo	T	Wave Length			
Viole	t 4000	Angstrom	units		
Elue	4500	""			
Gree	a 5200	44	10		
Yelh	w 5700	44	ee		
Red	6300	44	**		

The Augstrom unit — one ten-milliouth of a millimeter, i.e., 0.0000001 mm.

## ADJACENT SCALES FOR THE SOLUTION OF EQUATIONS OF THE FORM $f_1(v) = f_2(v)$

Equations of the above form may be solved by graduating both sides of one line in such a manner that a point on the scale will give values which satisfy the given equation. The scale equations are:

$$X_n = m_n f_1(u)$$
 and  $X_n = m_n f_2(v)$ 

Since  $f_1(u) = f_2(v)$  and  $X_u = X_v$ , i.e., for any point on the scale; then,  $m_u = m_v$ .

#### EXAMPLE 1

Consider the relation, 2.54I = C (Figure 23), where I represents inches and C represents continueters. Let I vary from 0 to 10; scale length, 6 in. If we rewrite the given equation so that

$$I = \frac{C}{2.54}$$

Then.

$$X_I = m_I I$$
, or  $6 \approx m_I 10$ 

from which

$$m_I = 0.6$$

Thus, the scale equation is  $X_I = 0.6I$ . The scale equation for C is  $X_c = 0.6(C/2.54) = 0.236C$ .



Fig. 26. Adjacent Scales for the Equation, 2.54I = C.

Note: Having computed the scale modulus for I, the same modulus must be used for C. If the scale modulus for C had been computed first, then this modulus would apply to I.

#### EXAMPLE 2

 $C = \pi D$  (Figure 27). C = circumference of a circle, with diameter D. Let D vary from 2 to 10 in. Scale length, 6 in.

The scale equations are:

$$X_c = m_c \left[ \frac{C}{\tau} \right]$$

and  $X_D = m_D D$ ; or  $6 = m_D [10 - 2]$ ;  $m_D = \frac{3}{4}$ hence  $X_D = \frac{3}{2} [D - 2]$ 

hence 
$$X_D = \frac{3}{4}[D-2]$$

and  $X_c = \frac{3}{4} \frac{C}{\pi} = \frac{3C}{4\pi} = 0.239C$ 

To locate a point on the scale C. For example, C = 10.

Point 10 on the C scale is 2.39 in. from the zero point of that scale  $(X_c = 0.239[10])$ . Since point 2 of the D scale is  $1\frac{1}{2}$  in,  $(X = \frac{3}{4} \times 2)$  from the zero point of the D scale, point 10 is (2.39 - 1.50) = 0.89 in.

Fig. 27. Adjacent Scales for the Equation,  $C = \pi D$ .

to right of point 2. (It should be observed that C = 0 when D = 0.) Yoint 20 of the C scale is 2.39 in. to the right of point 10 ( $X_c = 0.239 \times |20 - 10|$ ) = 2.39 in.). Points between 10 and 20 can easily be located by subdivision. Points beyond 20 can be located in a similar manner. Of course, a point of the C scale could be located by solving C from a specific value of D. The scale could then be graduated from the scale counties.

$$X_e = 0.239[C_2 - C_1]$$

#### EXAMPLE 3

U = sin V (Figure 28). Let V vary from 0° to 90°; scale length, ß in.

The scale equations are:

$$X_u = m_u U$$
 (1

and

$$X_v = m_v \sin V \qquad (2)$$

From equation (2)  $6 = m_v(\sin 90^\circ - \sin 0^\circ)$ ;  $m_v = 6$ . Hence the scale countions are:

$$X_u = 6U$$
  
 $X_u = 6 \sin V$ 

and



Fig. 28. Adjacent Scales for the Equation,  $U = \sin V$ .

# EXAMPLE 4

 $V = 4\pi r^2$  (Figure 29). V = the volume of a sphere of radius r. Let r vary from 0 to 5 in.; length of scale to be approximately 6 in. Then .

$$X_r = m_r r^2$$
; and  $X_u = m_* \frac{3V}{4\pi}$ 

$$m_r = \frac{6}{3.2 \, \text{K}} = 0.048.$$

For convenience, use  $m_{-} = 0.05$ . Then

$$X_r = 0.05r^3$$
 and  $X_v = 0.05 \times \frac{3V}{4\pi} = 0.0119V$ 

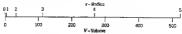
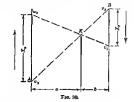


Fig. 29. Adjacent Scales for the Equation,  $V = \frac{4}{3}\pi r^2$ .

## NON-ADJACENT SCALES FOR THE SOLUTION OF EQUATIONS OF THE FORM

#### $f_1(u) = I_2(v)$

In the foregoing material it was pointed out that the same modulus was used in each scale equation. It may be desirable to use two dif-



ferent moduli. This can be done by separating the scales in the following manner. (See Figure 30.)

Let 
$$X_u = m_u f_1(u)$$
 (1)

and  $X_v = m_v f_2(v)$  (2)

 $u_0$  and  $v_0$  are zero values of the functions of u and v; and K is a point located on line AB so that any line passing through K and a selected point on the u or  $\sigma$  scale will cut the other scale in a value which satisfies the equation.

From the similar triangles Au, K and Br, K,

$$\frac{X_u}{X_r} = \frac{AK}{KR} = \frac{a}{h}$$

Therefore  $\frac{m_u f_1(u)}{m_u f_2(v)} = \frac{a}{b}$  (from equations 1 and 2 above)

Since  $f_1(u) = f_2(v)$ ,

$$\frac{a}{b} = \frac{m_u}{m_v}$$

Hence point K can be located on the diagonal AB by dividing it into the ratio

$$\frac{AK}{KB} = \frac{a}{b} = \frac{m_u}{m_e}$$

### EXAMPLE

Again consider the equation, 2.54I = C (Figure 31).

$$X_I = \frac{1}{2}I; \quad X_c = \left(\frac{2.51}{4}\right) \left[\frac{C}{2.54}\right] = \frac{C}{4}$$

$$\frac{m_I}{m_C} = \frac{\frac{1}{2}}{\frac{2.54}{A}} = \frac{1}{1.27}$$

#### EXERCISES

# Adjacent Scales or Non-Adjacent Scales

 Construct (a) adjacent and (b) non-adjacent scales for converting Fahrenheit readings to centigrade.

$$C = \frac{5}{9}(F - 32)$$
  $C(-40^{\circ} \text{ to } 100^{\circ})$ 

- Construct adjacent scales for the equation area of circle, A = πd²/4.
   to 20 in.). On not use log scales.)
- d(0 to 20 in.). (Do not use log scales.)
  15. Use logarithmic scales in problem 14. What are the advantages of each
- method? Disadvantages?

  16. Construct adjacent scales for the equation  $t = 2\pi \sqrt{L/g}$ , the period of a simple pendulum of length, L, and with g = 32.2. L (1 to 5 ft),
- 17. Construct adjacent scales for the equation, X' = log y. y(1 to 10).
- 18. On a log scale using the base 10, the distance between 1 and 2, 2 and 4, 4 and 8 are equal. Is this true when "o" is used as the base?
- Construct adjacent scales for the vapor pressure in air as a function of temperature as given in problem 10.
- 20. Construct non-adjacent scales for the compound interest law, P = A(1 + R)\*, where P is the principal, R the rate of interest, A the amount, and n the number of times compounded. Let A = \$1.00, R = 5%. Then P = (1.05)\*, n varies from 0 to 200. How can this chart he used if n = 30?

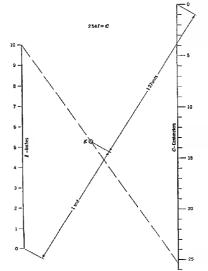


Fig. 31. Separated Scales for the Relation, 2.54I = C.

# Chapter Three

# ALIGNMENT CHARTS

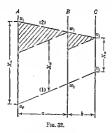
An alignment chart in its simplest form consists of three parallel scales so graduated that a straight line outling the scales will determine three points whose values satisfy the given equation.

In general, alignment charts may consist of three or more straightline scales, of curved scales, or of combinations of both.

# ALIGNMENT CHARTS FOR EQUATIONS OF THE FORM

$$f_1(u) + f_2(v) = f_3(w)$$

Suppose we have three parallel scales (Figure 32), A, B, and C, so graduated that lines (isopleths) 1 and 2 cut the scales in values which satisfy the equation  $f_1(u) + f_2(v) = f_3(w)$ . Now,



$$X_u = m_u[f_1(u_1) - f_1(u_0)]$$

$$X_{\rm c} = m_{\rm c}[f_2(v_1) - f_2(v_0)]$$

$$X_v = m_v[f_3(w_1) - f_3(w_0)]$$

If  $u_0, v_0, w_0$ , represent zero values of the functions, and if line 2 is any line, we may drop the subscripts and write simply

$$X_{\mathbf{u}} = m_{\mathbf{u}} f_{\mathbf{i}}(u) \tag{1}$$

$$X_{\nu} = m, f_2(v)$$
 (2)

Chapler 5

$$X_w = m_w f_2(w) \qquad (3)$$

Let us agree further that the spacing of the scales is in the ratio a/b. If we graduate the scales for  $f_1(u)$  and  $f_2(v)$  in accordance with their scale equations (1) and (2), respectively, what will be the modulus for the scale equation of  $f_2(u)$  and what will the cart on b equal if the chart satisfies this relation  $f_1(u) + f_2(v) = f_3(u)$ .

In Figure 32 draw lines through points w<sub>1</sub> and v<sub>1</sub> parallel to line u<sub>0</sub>v<sub>0</sub>. The shaded triangles are similar by construction, hence,

$$\frac{X_u - X_w}{X_w - X_v} = \frac{a}{b}$$

$$X_ub + X_va = X_w(a + b)$$

$$\frac{X_ub}{ab} + \frac{X_va}{ab} = X_w\left(\frac{a + b}{ab}\right)$$

$$\frac{X_u}{a} + \frac{X_v}{b} = \frac{X_w}{ab}$$

Since

or

$$X_u = m_u f_1(u)$$

$$X_u = m_u f_2(v)$$

$$X_w = m_w f_2(v)$$
  
 $X_w = m_w f_2(w)$ 

$$\frac{m_w f_1(u)}{a} + \frac{m_v f_2(v)}{b} = \frac{m_w f_3(w)}{ab}$$

If 
$$f_1(u) + f_2(v) = f_3(w)$$
, then

$$m_u = a_i$$
  $m_p = b$ 

Therefore 
$$\frac{a}{b} = \frac{m_v}{m_v}$$

and 
$$m_w = \frac{ab}{a+b} = \frac{m_w m_w}{m_w + m_w}$$

Thus, to construct an alignment chart for an equation of the form,  $f_1(u) + f_2(v) = f_3(w),$ 

- (a) Place the parallel scales for u and v a convenient distance apart. (b) Graduate them in accordance with their scale equations,
- $X_u = m_u f_1(u)$  and  $X_u = m_v f_2(v)$ . (c) Locate the scale for w so that its distance from the u scale is to
- its distance from the v scale as  $m_u/m_v = a/b$ . (d) Graduate the w scale from its scale equation,  $X_w = \frac{m_u m_v}{m_v + m_v} f_3(w)$ .

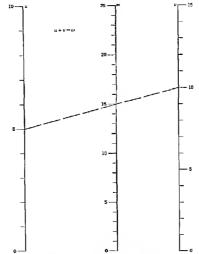


Fig. 33. Alignment Chart for the Equation, u + v = w.

#### EXAMPLE

u + v = w (Figure 33). Let u vary from 0 to 10; and v vary from 0 to 15. Suppose that the scale lengths are to be 6 in.

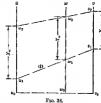
Now 
$$m_u = \frac{6}{1.6} = 0.6$$
;  $X_u = 0.6u$ 

and 
$$m_{-} = e^{0} = 0.4$$
;  $X_{+} = 0.4v$ 

and 
$$m_w = \frac{0.6 \times 0.4}{0.6 \pm 0.4} \approx 0.24; X_w = 0.24w$$

$$\frac{m_n}{m_n} = \frac{0.6}{0.4} = \frac{3}{2} = \frac{a}{b}$$

Now suppose that it is desirable to cut off the chart at the line 1



(Figure 34), eliminating the portion below line 1. The scale equations will then be (using line 1 as the base line):

$$X_u = m_u[f_1(u_2) \sim f_1(u_1)]$$

$$X_v = m_v[f_2(v_0) - f_2(v_1)]$$

$$X_w = m_w[f_3(w_2) - f_3(w_t)]$$

where  $u_1$ ,  $v_1$ , and  $w_1$  satisfy the equation  $f_1(u) + f_2(v) = f_3(w)$ .

#### EXAMPLE 1

u+r=w (Figure 35). Let u vary from 2 to 6; and r vary from 3 to 5. Length of scales, 6 in.

Now 
$$r_{*} = \frac{6}{6-2} = \frac{3}{2}; X_{*} = \frac{3}{2}(u-2)$$
  
 $r_{*} = \frac{6}{8-3} = \frac{6}{8}; X_{*} = \frac{6}{3}(r-3)$ 

n= - m,m,

Since

m = = 
$$\frac{3 \times 5}{3 + 5} = \frac{15}{21} = \frac{2}{3}$$

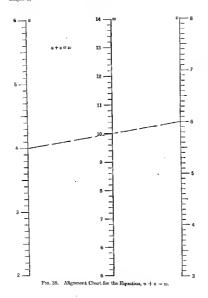
Since  $u_t = 2$  and  $v_t = 3$ , therefore  $w_t = 5$ . (From the original equation  $u + v = w_t$ ). Hence,  $X_{-} = 3(w = 5)$ 

$$\frac{a}{b} = \frac{m_b}{m_c} = \frac{3}{2} = \frac{5}{4}$$

Form the following tables:

	-	3	•	- 5	- 5
f.(+) = 4	2	3	4	5	5
X - 1 - 21	0	1 5 m	3 0 m	4 3 in	6 O to

<sup>\*</sup> Properties  $X_n = m_n f(u)$  Therefore,  $m_n = \frac{X_n}{f_n(u_n) - f_n(u_n)}$  In this case  $X_n = 6$  in, and  $f_n(u_n) - f_n(u_n) = (6 - 2)$ .



	3		4	1	ś	4		7		8
f <sub>2</sub> (v) = v	3		ı	- 1	5 6			7		8
X, = \$[s - 3]	0	1.2	in,	2.4	m.	3.6	in.	4.8	in.	6.0 in
19	1	8	[ ···	6	-	7			1	1
$f_3(w) = w$		5		6	_	ī			1	4
X <sub>w</sub> = {[ω -	- 5)	0	1	m.	+	m.			6	ia.

Much of the calculations set forth in the above tables can be eliminated if we compute the location of the end points for each scale, and then project the other points geometrically.

#### EXAMPLE 2

 $I = \frac{1}{15}bd^3$  (Figure 36), where I is the moment of inertia of a rectangle about its axis parallel to b, where b is the width, and d is the height of the rectangle.

Let b vary from 1 to 10 in, d from 1 to 10 in. Length of scales, 6 in. The equation, which may be written  $bt^3 = 12I$ , is put in the type form by taking legarithms; thus we obtain

$$\log b + 3\log d = \log I + \log 12$$

Now the moduli  $m_b$  and  $m_d$  are computed as follows:

$$m_b = \frac{6}{\log 10 - \log 1} = 6; X_b = 6 \log b$$

$$m_d = \frac{6}{3 \log 10 - 3 \log 1} = 2; X_d = 2(3 \log d) = 6 \log d$$

It should be pointed out that the function of d is 3 tog d, the modulus 2 is the "actual modulus" which is used in locating the I scale, and the coefficient  $\theta$  is the effective modulus which is used in graduating the d scale.

$$m_I = \frac{6 \times 2}{6 + 2} = \frac{12}{8} = \frac{3}{2}; \quad X_I = \frac{3}{2} (\log I + \log 12)$$

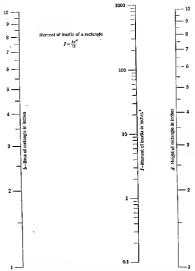


Fig. 36. Moment of Inertia of a Rectangle about Its Axis Parallel to the Base.

Note carefully that the actual moduli of b and d are used in computing  $m_b$ . Form the following table:

6	Į 2		3	 10	
f(b) = log b	0	0.301	0.477	1.000	
$X_k = 6 \log b$	0	0.81	2 86	6,00	

The table for d will be the same as the above since  $m_d = 6$  (effective modulus).

Now we can graduate the scales for b and d in accordance with the scale equations  $X_s = 6$  bug hand  $X_s = 26$  leg of . The scales are placed a convolent distance apart. The position of the I scale is determined from the ratio  $m_s m_{HH} = \frac{9}{2} = \frac{9}{2}$ . Our next step is to locate one point and the I scale, i.e., point 1. Suppose we let d = 2. Then  $b = 12I/I_0^2$  or  $b = (12 \times 1)I/6 = 1.5$ . The line joining b = 1.5 and d = 2 such that I scale at point 1. Now we can locate other points on the I scale from the scale security.

$$X_I = \frac{6 \times 2}{6+2} [\log I - \log 1]$$

or 
$$X_I = 1.5(\log I)$$

This means that points on the I scale are laid off from point 1. If the selected point on the I scale were 10, then graduations would be laid off from this point in accordance with the scale equation:

$$X_I = 1.5[\log I - \log 10]$$
  
 $X_I = 1.5[\log I - 1)$ 

or

If the equation were  $f_1(u) - f_2(v) = f_3(w)$ , the scale equations would be:

$$X_u = m_u f_1(u) \qquad (1)$$

$$X_v = m_v [-f_2(v)]$$
 (2)

$$X_w = \frac{m_u m_v}{m_u + m_v} f_3(w) \qquad (3)$$

The negative sign in equation 2 implies that positive values of  $f_2(v)$  are laid off downwardly if we agree to lay off positive values of  $f_1(u)$  upnardly.

#### EXAMPLE

u-v=w (Figure 37). Suppose u varies from 0 to 5, and v varies from 2 to 6. Scale lengths, 6 units (inches, continueters, or any convenient length).

$$\begin{split} &m_u = \frac{6}{5}, \ \ X_o = \frac{6}{5}u \\ &m_p = \frac{6}{4} = \frac{3}{2}; \ \ X_r = \frac{3}{2}(-v) = -\frac{3}{2}v \\ &m_{ss} = \frac{6}{5} \times \frac{3}{2} = \frac{8}{215} = \frac{2}{3}; \ \ X_o = \frac{3}{3}w \\ &\frac{m_{ss}}{2} = \frac{6}{5} = \frac{4}{5} \end{split}$$

Scales u and v are placed a convenient distance apart. Scale u is graduated in accordance with the scale equation  $X_u = \frac{e}{N}u$ . Scale v is



Fig. 37. Alignment Chart for the Equation, u - v = v.

graduated from the equation  $X_v = \frac{3}{2}v$ . This is done by locating point 2 on the upper end of the v scale, and laying off distances equal to  $\frac{3}{2}$  units for each point 3, 4, 5, and 6.

NOTE: POSITIVE VALUES OF "P" ARE LAID OFF DOWN-WARDLY!

A point on the w scale can be located by solving the original equation, w - v = w,

Example: Let u = 3 and v = 4; then w = -1 (of course, in this case it might have been simpler to locate the zero point on the v scale by letting u and v equal the same value). Having located one point on v, other points can be located from the scale equation  $X_v = \frac{\pi}{2}w$ ; that is, the distance between consecutive points is  $\frac{\pi}{2}$  units.

# EXERCISES

# Hydraulics

21(a).  $Q = 3.33 hH^{34}$  (Francis weir formula for a rectangular weir)

where Q = discharge (cubic feet per second), b = width of werr (3 to 20 ft), H = head above creet (0.5 to 1.5 ft).

21(b). Use a double graduation of the Q scale of part a to indicate gallons per manute.

V = C√2gH (velocity of water, in feet per second, through an ordice due to a head of water. H)

where g = 32.2, C = a coefficient for the orifice depending on shape, etc. (0.6 to 1), and H = head of water (1 to 15 tt)

23. The horsepower of a jet of water is given by the equation

$$\mathrm{HP} = \frac{\mathrm{W}^2}{2g \times 550}$$

where W = the weight of water per second (1 to 100 lb) and v = the velocity of water in feet per second (1 to 50).

If desired, since one cubic foot of water is 62.4 lb, the furnula may be converted to

$$\mathbf{HP} = \frac{Qv^3 \times 624}{2g \times 550}$$

where Q = the quantity in cubic feet per second and q = 32.2.

21.  $H = \frac{P}{W}$  (head in feet of a liquid equivalent to the pressure, P, in pounds per square foot)

where W is weight per cubic foot of the liquid. If P is in pounds per square inch, H=144P/W.

Let P vary from 5 to 300 psi. For W use the common fluids such as water and kerosene.

25. 
$$H = 0.38 \frac{V^{1.80}}{r_{3.28}}$$
 (friction head for water flowing in 1000 ft of pipe)

where V = velocity of flow in feet per second (2 to 15) and D = diameter of pipe in feet (1 to 6).

# Strength of Materials

26. 
$$E_s = \frac{\pi}{r} d^2f_s$$
 (allowable strength of a rivet)

where d = diameter of rivet (26 to 1 in.) and  $f_s =$  allowable unit shearing stress of material (3000 to 15,000 psi).

27. 
$$\rho^2 = \frac{I}{A}$$
 (radius of gyration of a section)

where I = moment of inertia (1 to 1000 in.4) and A = area of section (1 to 100 sq in.).

28. 
$$f = \frac{C\pi E}{\left(\frac{L}{F}\right)^2}$$
 (critical stress in a long column)

Let C=1, fixity coefficient for pin ended column, E= modulus of elasticity (10  $\times$  10<sup>6</sup> to 30  $\times$  10<sup>8</sup> psi), and (L/P)= stenderness ratio (70 to 200).

29. 
$$e = \frac{f_x}{E} - \frac{mf_x}{E}$$
 (unit elongation in the x direction)

where  $f_x = \text{unit stress in } x \text{ direction (0 to 50,000 psi)}, f_y = \text{unit stress in } y \text{ direction (0 to 50,000 psi)}, m = 0.3, and <math>B = 30 \times 10^6 \text{ psi for structural steel.}$ 

### Mechanical

30. BHP =  $\frac{d^3n}{2\pi}$  (Association of Automobile Manufacturers formula)

where  $d = \text{diameter of cylinders } (1^0_4 \text{ in. to } 5\%), n = \text{number of cylinders } (2, 4, 6, 8, 12), and BHP = brake horsepower.$ 

31. 
$$d = 2.87 \sqrt[3]{\frac{HP}{RPM}}$$
 (diameter in inches of a spur gear steel shaft)

where HP = horsepower (100 to 2000) and RPM = revolutions per minute (100 to 1000).

32. 
$$P_m = \frac{(1 + \log_e R)}{R} P_1$$
 (absolute mean pressure of expanded steam)

where  $P_1$  = absolute initial pressure (50 to 350 psi) and R = ratio of expansion =  $\nabla/V_1$  (1 to 10).

33.  $P = CF^{1/2}D^{1/2}$  (pressure in pounds on tool when cutting cast iron)

where F = feed (0.01 to 0.20 in.), D = depth of cut (1 to 1 in.), C = 45,000for soft cast iron, and C = 69,000 for hard cust iron.

34. 
$$P = \frac{P^{6.57}A_3}{60}$$
 (flow of steam through a steam nostle in pounds per

where P = absolute initial pressure (5 to 300 psi) and  $A_0 =$  area at throat (I to 30 sq in.).

35. 
$$E = \frac{\pi DN}{12}$$

38

where S is the cutting speed in feet per minute in lath or boring mill, D = diameter of work (0.25 to 12.5 in.), and N = (10 to 1000 rom)Civil

36.  $C = 0.0000065L(T - T_0)$  (change in length of a steel tape due to a difference in temp

 $[T - T_0]$  from the standard temperature,  $T_0$ ) where L is the measured length (10 to 100 ft), and (T

- Ta) varies from (5° to 75"). 37. In the figure shown it is required to find the inac-

cessible distance BD, which is equal to BD = BC /AB. BC varies (1 to 10) and AB varies (1 to 10). 38. For the simple curve  $T = R \tan \Delta/2$ , where R is usually obtained from

the degree of curvature and is equal to

$$R = \frac{5729.65}{\text{(degree of curv.)}} = \frac{5729.65}{D}$$

where D, degree of curvature, varies (1° to 30") and  $\Delta$  varies (10° to 150").



39. L.C. =  $2R \sin \frac{\Delta}{2}$  (long chord as shown in figure of problem 38)

Use limits of problem 38,

40. 
$$C = R \operatorname{exsec} \frac{\Delta}{2} \text{ (external distance of a curve)}$$

See figure of problem 38. Use same limits.

41. 
$$M = R \text{ vers } \frac{\Delta}{2} \text{ (midordinate of a curve)}$$

See figure of problem 38. Use same limits.

42. 
$$L = \frac{\Delta}{5}$$
 100 (length of the curve)

See figure of problem 38. Use same limits.

43. 
$$R = \frac{50}{\sin \frac{D}{r}}$$
 (radius of curvature for 100-ft chords)

See figure of problem 38. Use same limits.

44. 
$$R = \frac{\frac{C}{2}}{\sin \frac{CD}{200}}$$

where it is recommended that

$$C = 100$$
 ft for  $0^{\circ} < D < 7^{\circ}$ 

$$C = 25 \text{ ft for } 14^{\circ} < D < 28^{\circ}$$

$$C = 10 \text{ ft for } D > 28^{\circ}$$

45. In a railroad curve as shown the offset x of B from the tangent at A is



where C varies (10 to 100 ft) and R varies (100 to 6000 ft)

# Cleetrical

40

46.  $F = \frac{E^*}{R}$  (power in watts used in passing an electric current through a resistance, R)

where E = voltage (10 to 220 volts) and R = resistance (10 to 1000 ahms).

47. 
$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} \text{ (sum of resistances in parallel)}$$

where R1 (1 to 100 ohms) and R2 (1 to 100 ohms).

48. 
$$X = \frac{1,000,000}{2\pi fC} \text{ (reactance of a coil)}$$

where f= frequency, cycles per second (30 to 3000) and C=(1 to 100) capacity of condenser, in microfurads

49.  $E = 0.332 \log \frac{d}{0.78r}$  (inductive volts per ampere per nule of line with two wires for a 25-cycle current)

where r = the radius of the wire in lockes and d = the spacing in inches (4 to 100). Express r in R and S gags numbers, which vary f con (6000 to 10). 59. Double-graduate the E scale of problem 49 to solve the formula, when using a 60-cycle current:

$$E = (0.232 \times 3.4) \log \frac{d}{0.228}$$

# Acronautical

51.  $q = \frac{\rho V^2}{2}$  (dynamic pressure of air moving at velocity V)

where  $\rho=$  air density slags per cubic foot (0.0010 to 0.0025) and V= velocity of air, feet per second (30 to 300).

52. 
$$R = \frac{S^2}{4}$$
 (aspect ratio of wing)

where S= span of airplane wing m feet (20 to 100), A= area of airplane wing m square feet, and B= aspect rate (4 to 7).

53. Since  $V_{\rm max} = \frac{\pi e}{4\pi} V_{\rm rye}$  and 1 slug = 32.2 lb, double-graduate the  $\rho$  and V scales of problem 51 to increase the usefulness of the chart by eliminating the conversion of units.

54. 
$$V_s \approx 20 \left( \frac{S}{C_{L_{\text{genge}}}} \right)^{3/2} \text{(stalling speed of an airplane in feet per second)}$$

where S= wing loading, pounds per square foot (5 to 40) and  $G_{L(\max)}=$  maximum lift coefficient (1.1 to 2.5).

55. 
$$m = m_0 - \frac{4}{3 + \frac{6}{R}}$$
 (clope of lift curve for aspect ratio,  $R$ )

where  $m_0 \approx \text{slope } dC_L/d$  at aspect ratio 6, range (4 to 7), and R = aspect ratio (4 to 7).

56. When the equation of problem 56 is constructed as a Z type, it is possible by the proper selection of moduli to make all scales uniform. Show how this can be done.

57. 
$$F_b = \left[1.35 - 0.01 \frac{d}{t}\right] \cdot \text{fatt. T.S.} \text{ (allowable stress in bending}$$
  
in a chrome molybdenum steel tube)

where d/t = diameter/thickness of wall = thickness ratio (10 to 30) and ult. T.S. = ultimate tensile strength of material (90,000 to 180,000 psi).

#### General

Chapter 31

 I = ½Wr² (moment of inertia of a right circular cylinder about its axis)

where W = total weight in pounds (1 to 25,000) and  $\tau = \text{radius}$  in inches (1 to 25),

59. 
$$r = \sqrt{x^2 + y^2}$$
 (vector r whose co-ordinates are x and y)

where x varies (0 to 10), y varies (0 to 10).

60. 
$$V = 2.467Dd^2$$
 (volume of a torus)

where D= larger diameter of torus (1 to 10) and d= small diameter of torus (1 to 10).

61. 
$$I = \frac{bd^2}{12} \text{ (moment of inertia of rectangle)}$$

where I= moment of inertia in inchest, b= width of rectangle (2 to 16 in.), and d= depth of rectangle (4 to 24 in.).

62. 
$$P = A(1+R)^n$$
 (principal  $P$  after  $n$  compoundings of the amount  $A$  at the rate of interest,  $R$ )

Let A=\$1.00, R= interest rate in % (1 to 8), and n= number of times compounded (1 to 20).

#### Chemical

42

μ = μ<sub>1</sub>\* (specific viscosity referred to water with the same temperature of a salt solution whose normality is n)

where  $\mu_i$  is the specific viscosity of a normal solution and may be determined from Perry's Chemical Engineers' Handbook, p. 670 (1934), for various salt solutions and setch at  $25^{\circ}\mathrm{C}_{3}$  a varies (0.1 to 1.0), and  $\mu$  varies (0.95 to 1.45).

64.  $V = 174.24\sqrt{t + 459.6}\sqrt{H}$  (velocity of air at or near atmospheric pressure)

where V=(300 to 15,000 ft per min),  $t\simeq \text{temperature in degrees Fahrenbeit-range } (0^{\circ} \text{ to } 1000^{\circ})$ , and H=velocity bead in inches (0 to 5).

65.  $V_1 = V \sqrt{\frac{P}{P_1}}$  (corrected velocity of problem 64 for pressures considerably above atmospheric)

where  $V_1 = (100 \text{ to } 10,000 \text{ ft per min})$ , V = as before, problem 64,  $P = (14.7 \text{ to } 100 \text{ ps}_1)$ , and  $P_2 = 14.7 \text{ ps}_1$ .

66.  $V_2 = V_1 \sqrt{\frac{1}{S}}$  (correction of  $V_1$  of problem 65 for specific gravity)

where  $V_1=$  (100 to 20,000 ft per min),  $V_1=$  (as before), and S= (0.2 to 1.6), relative to air.

67. P = M (10.82 - 4425) (partial pressure of ammonia in atmosphere over a solution of M gram moles of ammonia per 1000 grams of water; T is the temperature in degrees centicated absolute)

when P = (0 to 1000 mm), M = (0 to 100 grams), and  $T = (10^{\circ} \text{ to } 40^{\circ}\text{C})$ . Note that the limits of P, M, and T are not given in the units to be used in the equation. Therefore revies the equation, noting that 1 atmosphere = 760 mm, molecular weight of  $NH_3 = 17.0$ , and zero degree absolute centigrade =  $-273^{\circ}\text{C}$ .

#### Statistics

68. 
$$\sigma_y = \sqrt{\frac{\Sigma y^2}{N}}$$

where  $\sigma_y = \text{standard deviation from mean } (0.05 \text{ to } 1000), <math>\Sigma y^2 = \text{sum of deviations squared } (1 \text{ to } 10^4), \text{ and } N = \text{number of cases in sample } (1 \text{ to } 1000).$ 

69. 
$$\sigma_{xx} = \sigma_y \sqrt{1 - \tau_{xy}^2}$$
 (standard error of estimate in predicting y scores from  $z$ )

where  $\sigma_y$ , standard deviation of y scores (1 to 20);  $\tau_{xy}$  correlation of x and y scores (0.50 to 0.99), and  $\sigma_{yy}$  standard error of estimate (1 to 20).

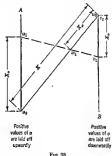
# Chapter Four

# ALIGNMENT CHARTS (Z CHARTS) FOR THE SOLUTION OF EQUATIONS OF THE FORM

$$f_1(u) = f_2(v) \cdot f_3(w)$$

Suppose that the parallel scales (Figure 38), A and B, are graduated in accordance with their scale equations,  $X_n = m_n f_1(u)$  and  $X_n =$  $m_v f_2(v)$ , respectively. The diagonal scale for  $f_3(w)$  joins  $f_1(u_0)$  and  $f_2(v_0)$ , i.e., the zero values of the functions of u and v.

Let us suppose further that a straight line joining points u1 and v1 cuts



the diagonal scale in point  $w_1$  so that the equation  $f_1(u) = f_2(v) \cdot f_3(w)$ is satisfied. What will be the scale equation for f3(w)?

From the similar triangles unutur and vorter.

$$\frac{X_u}{X_v} = \frac{K - X_w}{X_w}$$

or 
$$X_u = X_v \frac{(K - X_u)}{X_w}$$
  
since  $X_u = m_u f_1(u)$   
and  $X_v = m_u f_2(v)$ 

Then 
$$m_u f_1(u) = m_u f_2(v) \frac{(K - X_u)}{X_u}$$

If 
$$f_1(u) = f_2(v) \cdot f_3(w)$$

then 
$$\frac{K - X_w}{X_w} = \frac{m_u}{m_v} f_2(w)$$

from which 
$$X_w = \frac{Km_v}{m_v f_0(w) + m_v}$$

or 
$$X_w = \frac{K}{\frac{m_w}{m_x} f_2(w) + 1} = \frac{K}{K_1 f_2(w) + 1}$$

where 
$$K_2 = \frac{m_u}{m_v}$$

If it is desired to graduate the w scale from  $u_0$  instead of  $v_0$ , it can be shown that the distance from  $u_0$  to  $w_1$  is equal to

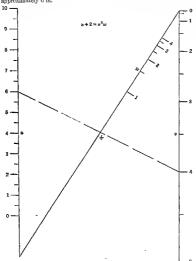
$$\frac{Km_u f_3(\omega)}{m_u f_3(\omega) + m_s}$$
 (This should be verified by the reader.)

- From the above one can construct this type of chart in the following manner:
- Draw scales for the variables, u and v, parallel to each other.
   Graduate the u scale in accordance with its scale equation, X<sub>u</sub> = m<sub>t,f</sub>(u)
  - (3) Graduate the ν scale in accordance with its scale equation, X<sub>ν</sub> = m<sub>ν,f</sub><sub>2</sub>(ν) (plotting positive values of ν downwardly if positive values of ν were plotted unwardly.
  - (4) Graduate the w scale from  $v_0$  in accordance with its scale equation,  $X_w = \frac{K}{K_1 f_2(w) + 1}, \text{ or from } v_0 \text{ in accordance with the scale}$

equation, 
$$X_w = \frac{Km_w f_3(w)}{m_w f_3(w) + m_v}$$

# EXAMPLE 1 -

Consider the equation  $(u+2)=v^2u$  (Figure 39). Suppose that u varies from 0 to 10, and v from 0 to 5. The scale lengths are to be approximately 6 in.



Fro. 39. Z-type Chart for the Equation, (14 + 2) =  $e^2 \omega$ .

$$m_u = \frac{6}{(10+2)-(0+2)} = 0.6$$

 $m_r = \frac{6}{25} = 0.24$ . (We shall use 0.25, which merely lengthens the scale from 6 to 6.25 in.)

Hence.

$$X_u = 0.6(u + 2)$$
  
 $X_v = 0.25v^2$ 

and

$$X_w = \frac{10}{\frac{0.6w}{0.25} + 1} = \frac{10}{\frac{12w}{5} + 1}$$

where K = 10 (ten of any convenient unit).

Form the following table:

ی	0	0.5	1	2	3
X.	10	ŧ÷	47	38	75

### EXAMPLE 2

Let us consider the equation for the volume of a right circular cylinder,  $V \sim \pi r^2 h/144$ , where V is the volume in cubic feet, r is the radius of the base circle, in inches (4 to 12), and h is the height of the cylinder in feet (4 to 15). We may write the equation,

$$KV = r^2 h$$
, where  $K = \frac{144}{r}$ 

The range of V is determined from the ranges of r and h. Simple calculations will show that V varies from 1.40 (or 4x/9) cubic feet to 47.15 (or 15x) cubic feet.

Now

$$m_{\tau} = \frac{10 \pm}{\frac{144}{\pi} \left( 15\pi - \frac{4\pi}{9} \right)} = 0.005$$

$$X_{\tau} = 0.005 \left[ \frac{144}{\pi} \left( V - \frac{4\pi}{9} \right) \right]$$

and

$$m_r = \frac{10 \pm 1}{144 - 16} = 0.08$$

$$X_r = 0.08[r^2 - 4^2]$$

From the above scale equations, we can graduate the V and r scales. It will be observed that it is necessary only to compute the total length  $A = \frac{1}{2} \left( \frac{1}{2} A + \frac{1}{2} A +$ 

of the V scale; i.e., 
$$x_s = 0.005 \left[ \frac{134}{2} \left( 15\pi - \frac{4\pi}{9} \right) \right] = 10.48$$
. Then we know that the lower point of the scale will be marked 4.40 and the upper point will be marked 47.15. Additional graduations can be obtained

by proportion. Since the function is linear, the scale is uniform.

In the case of the r scale, it should be noted that the function is r², and therefore distances between consecutive points are proportional to

and therefore distances between consecutive points are proportional to the square of r.

The location of the diagonal scale must be determined next. Many

students raise the typical error of connecting point 4 on the r scale with point 1.40 on the V scale. Romember that the diagonal line joins to not have been considered to the function of V. These points would be zero on the V scale. In this case, it would be possible to include disase points on the reacle and zero on the V scale. In this case, it would be possible to include disase points on the respective scales. However, often the zero values of the functions are not accessible within the limits of the drawing. Let us assume this to be the stan in our problem.

The position of the h scale can be established by a very simple method. Let us locate points 6 and 12 on the h scale. If we let r=10, then V=13.1 when h=6. The line joining r=10 with V=13.1 contains h=6. Again, if we let r=12, then V=18.9 so when h=6. The line joining r=12 with V=18.0 contains h=6. Therefore, the intersection of these two lines is h=6 and, in addition, is a point on the diagonal. This method can be repeated for another point such as h=10. Other points on the h=10 can then point such as h=10. Other points on the h=10 can then be located from point 12, by properly using the scale equation,

$$X_h = \frac{K}{\frac{m_3}{m_7}h + 1} = \frac{K}{\frac{0.005}{0.08}h + 1}$$

It is evident that K must be determined. This can be done, since the distance between points 6 and 12 can be measured. Hence,

$$\frac{\frac{K}{0.005} \times 6 + 1}{\frac{0.005}{0.08} \times 12 + 1} = 2.37$$

from which K = 15.23,

from

 $X_{h} = \frac{15.23}{0.005} \frac{243.68}{h+1} = \frac{243.68}{h+15}$ 

	5	6	7	8	Ð	10	11	12	13	14	18
12 18	11 59	11 07	10 53	10 13	9.73	9 36	9 01	8 70	5 40	B 12	7,86
3 45	2 89	2 37	1.83	1.43	1 03	0.66	031	0	0.30	0 58	984
	-							· <del>─</del> ┟─ <del>╎</del> ─┤─┤─		<del></del>	12 15 11 50 11 07 10 55 10 17 0.73 9 36 9 01 8 70 5 40 8 12 3 45 2 59 2 37 1.83 1.43 1 03 0.06 0 31 0 0.30 0 58

The alignment chart is shown in Figure 40.



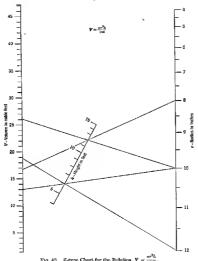
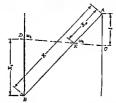


Fig. 40. Z-type Chart for the Relation,  $V = \frac{\pi r^2 \hbar}{144}$ .

#### SIMPLIF ... METHOD

A method which may simplify the work of graduating the diagonal scale can be developed in the following manner (Figure 41). Let C be



Fro 41.

a fixed point on the right vertical scale. Let the distance from point A to the fixed point be I (inches, centimeters, or any other convenient number of units). Suppose that the right-scale side of the left vertical scale carries a temporary w scale. From the similar triangles, BDE and ACE.

$$\frac{X_1}{t} = \frac{K - X_w}{X_w}$$

$$X_1 = t \left[ \frac{K - X_w}{V} \right]$$

Previously it had been shown that

$$\frac{K-X_w}{X_w}=\frac{m_u}{m_u}[f_3(w)]$$

Hence.

$$X_1 = l \frac{m_u}{m_s} [f_3(w)]$$

This equation enables us to graduate the temporary w scale. Lines joining the fixed point, C, with the graduations on the temporary scale will intersect the diagonal in points having the same values of w.

This method has two advantages over the one of locating points on the diagonal from the equation,

$$X_w = \frac{K}{\frac{m_u}{m_v} f_3(w) + 1}$$

First, if the function of m is linear, a uniform scale can be graduated on the temporary scale; second, the length, K, of the diagonal scale need not be known.

# EXAMPLE

 $B = \frac{\tilde{a}^2 n}{2.5}$  (formula taken from the Association of Automobile Manufacturing)

where B represents brake horsepower, d (0 to 5 in.) the diameter of the cylinder in inches, and n (2, 4, 6, 8, 10, 12) the number of cylinders. The maximum value of B=120. Suppose that the lengths of the parallel scales, B and d, are 7.5 in. The scale equations will be:

$$X_B = m_B(2.5B); 7.5 = m_B(300); m_B = \frac{7.5}{300} = 0.025$$

$$X_d = m_d(d^2); \quad 7.5 = m_d(25); \quad m_d = \frac{7.5}{25} = 0.3$$

(a) Applying the first method, K = 9 in., we have

$$X_n = \frac{9}{\frac{0.025}{0.3}n + 1} = \frac{9}{\frac{n}{12} + 1} = \frac{108}{n + 12}$$

Form the following table. (Plot n from these values.)

n	2	4	6	8	10	12
X,	7.71	6.75	6.00	5.40	4.91	4.50

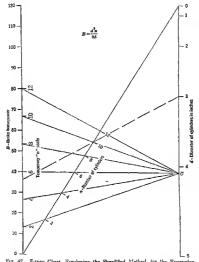
(b) Applying the second method, we obtain

$$X_1 = l \frac{m_S}{m_d} \cdot n; X_1 = 5 \times \frac{0.025}{0.3} \cdot n = \frac{5n}{12}$$

Points on temporary scale  $X_1 = \frac{r}{12}n$  are located on the right-hand side of the B scale. These points are connected with the fixed point, C. The intersection of these lines with the diagonal locate the points on the n scale. In this example, l = 5 in. (See Figure 42 for completed chart.)

# EXERCISES

Since most of the problems of the "three parallel scales" type also fall in the Z type, construct Z-type charts for: Problems 22 to 29, inclusive; 31 to 45, inclusive; 47, 50 to 57, inclusive; 60 on 60, inclusive; 65 and 69.



Fro. 42. Z-type Chart, Eurpleying the Simplified Method, for the Expression,  $B=\frac{d^2 a}{2.5}\,.$ 

the B scale. These points are connected with the fixed point, C. The intersection of these lines with the diagonal locate the points on the n scale. In this example, l=5 in. (See Figure 42 for completed chart.)

#### EXERCISES

Since most of the problems of the "three parallel scales" type also fall in the Z type, construct Z-type charts for. Problems 22 to 23, inclusive; 31 to 45, inclusive; 47; 50 to 57, inclusive; 60 to 65, inclusive; 68 and 69.



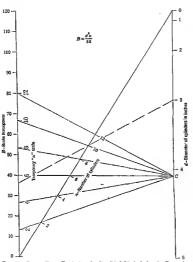


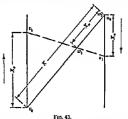
Fig. 42. Z-type Chart, Employing the Simplified Method, for the Expression,  $B = \frac{d^2n}{2.5}.$ 

# Chapter Five

# OTHER FORMS OF EQUATIONS WHICH CAN BE SOLVED BY A Z CHART

$$f_1(u) + f_2(v) = \frac{f_1(u)}{f_2(w)}$$

Let us consider Figure 43, which shows the  $\epsilon$  scale on the left, graduated in accordance with the scale equation  $X_t = m_t f_t(\epsilon)$  and the u scale on the right, graduated from the scale equation,  $X_t = m_t f_t(u)$ . Note that positive values of the variable,  $\epsilon$ , are plotted upwardly, and that



• 10. 45

positive values of the variable, u, are plotted downwardly. The diagonal scale which carnes the graduations for the function of w joins the zero values of the functions of u and c.

What is the scale equation for the function of w, in order to have co-linear points on the w, v, and w scales satisfy the given equation

$$f_1(u) + f_2(v) = \frac{f_1(u)}{f_3(w)}$$

From the similar triangles vov w, and uou, w, it follows that

$$\frac{X_{v}}{X_{u}} = \frac{K - X_{w}}{X_{w}}$$
If  $X_{u} = m_{s}f_{1}(u)$ 

$$X_{v} = m_{s}f_{2}(v)$$
and  $X_{w} = m_{s}f_{2}(v)$ 
then 
$$\frac{m_{s}f_{2}(v)}{m_{s}f_{1}(u)} = \frac{K - m_{w}f_{2}(w)}{m_{w}f_{2}(w)}$$
or 
$$\frac{m_{s}f_{1}(u) + m_{s}f_{2}(v)}{m_{s}f_{2}(u)} = \frac{K}{m_{s}f_{2}(w)}$$
and 
$$m_{s}f_{1}(u) + m_{s}f_{2}(v) = \frac{Km_{w}f_{1}(u)}{m_{w}f_{2}(w)}$$

If 
$$K = m_v$$
 and  $m_u = m_v$   
then  $f_1(u) + f_2(v) = \frac{f_1(u)}{f_1(u)}$ 

then 
$$f_1(u) + f_2(v) = \frac{f_2(w)}{f_2(w)}$$

Therefore to construct a chart of this form, graduate the scales in accordance with the scale equations:  $X_n = m_n f_n(u)$ 

$$X_{v} = m_{u}f_{2}(v)$$

$$X_{w} = Kf_{8}(w)$$

#### EXAMPLE

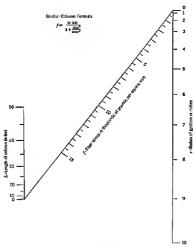
$$f = \frac{20,000}{1 + \frac{144L^2}{9000r^2}}$$
(Gordon Column Formula)
$$L \text{ (0 to 50 ft)}$$

$$r \text{ (0 to 10 in.)}$$

This equation can be reduced to the form

$$r^2 + 0.016L^2 = \frac{r^2}{\frac{f}{20,000}}$$

The equation is the same form as the type which was developed above.



F10. 44. Gordon Column Formula.

The scale equations are:

$$X_r = m_r r^2$$
  
 $X_L = m_r (0.016L^2)$ 

(Remember that the moduli for the parallel scales are the same.)

$$X_f = K\left(\frac{f}{200000}\right)$$

If the length of the  $\tau$  scale is 7.5 in., then

$$m_r = \frac{7.5}{(10)^2} = 0.075$$

or 
$$X_r = 0.075r^2$$

Now 
$$X_L = 0.075(0.016L^2) = 0.0012L^2$$

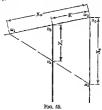
then

$$Z_f = 8\left(\frac{f}{20,000}\right) = 0.0004f$$

The chart is shown in Figure 44. If the equation is of the form.

$$f_1(u) - f_2(v) = \frac{f_1(u)}{f_3(w)}$$

the scales for u and v will be graduated in the same direction as shown below (Figure 45).



#### EXERCISES

70. Bazin coefficient for velocity in open channel flow:

$$C = \frac{87}{0.552 + \frac{m}{4 \sqrt{3}}}$$

where m = coefficient of roughness (0.06 to 2) and R = bydraulic radius in fact (0.2 to 25).

71. S.G. = 
$$\frac{W}{W - W'}$$
 (specific gravity of a body)

where W = weight in air (0 to 10), W' = weight in water (0 to 10), and S.G. varies (1 to 15).

72. 
$$\left(\frac{d}{t}\right) = \frac{2f - P}{P}$$
;  $\left[\left(\frac{d}{t}\right)\right]$  required for a thick-walled tube subjected to

internal pressure where 
$$\frac{d}{i}$$
 is more than 4

where  $f=\max$  maximum fiber stress of material (5000 to 60,000 psi), P= internal pressure (1000 to 10,000 psi), and  $(d/\ell)$  varies from 4 to 12.

# Chapter Six

# ALIGNMENT CHARTS FOR THE SOLUTION OF EQUATIONS OF THE FORM

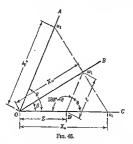
$$\frac{1}{f_1(u)} + \frac{1}{f_2(v)} = \frac{1}{f_3(w)}$$

Suppose that the intersecting scales, A and C, are graduated in accordance with the scale equations (Figure 46):

$$X_u = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

If a straight line joining points  $u_1$  and  $v_1$  intersects scale B in a point



 $w_1$  so that the given equation is satisfied, how should the w scale be graduated and how is it located?

Through  $w_1$  let us draw a line parallel to scale A. From the similar triangles  $Ou_1v_1$  and  $Dw_1v_1$ ,

$$\frac{X_u}{X_u} = \frac{X_v - Z}{\ell}$$

$$X_t \ell = X_u X_v - X_u Z$$

$$\frac{1}{X_u} = \frac{1}{\ell} - \frac{Z}{X_u \ell}$$

$$\frac{1}{m_b f_1(u)} + \frac{Z}{m_b f_2(u) \ell} = \frac{1}{\ell}$$

$$\frac{1}{f(u)} + \frac{Zm_u}{m_b f_2(u) \ell} = \frac{m_u}{\ell}$$

In order that the second term of the left-hand member shall become  $1/j_2(v)$ ,

let

$$\frac{Z}{\ell} = \frac{m_v}{m_u}$$

from which

$$\ell = \frac{Zm_u}{m_v}$$

Hence,

$$\frac{1}{f_1(u)} + \frac{1}{f_2(v)} = \frac{m_v}{Z}$$

$$Z = m_v f_3(w)$$

11 then

$$\frac{1}{f_1(u)} + \frac{1}{f_2(v)} = \frac{1}{f_3(w)}$$

Therefore, to construct a chart of the above form:

(a) Graduate the scales for  $f_1(u)$  and  $f_2(v)$  in accordance with their scale equations,  $X_u = m_u f_1(u)$  and  $X_v = m_v f_2(v)$ , respectively.

(b) Locate the scale for f3(w) so that

$$\frac{Z}{\ell} = \frac{m_v}{m_v}$$

(c) Graduate the C-scale (see Figure 46) with a temporary w scale, using the scale equation,  $Z=m_v f_3(w)$ , and project the points of this scale onto the w scale by means of parallels to the scale A.

#### ALTERNATE METHOD

A method for graduating the w scale directly can be developed in the following manner:

By trigonometry,  

$$X_u^2 = Z^2 + \ell^2 - 2Z\ell \cos(180^\circ - \theta)$$

$$= Z^2 + \left(Z\frac{m_*}{m_*}\right)^2 - 2Z^2\left(\frac{m_*}{m_*}\right)(-\cos\theta)$$

$$= Z^2\left[1 + \left(\frac{m_u}{m_*}\right)^2 + 2\left(\frac{m_u}{m_*}\right)\cos\theta\right]$$

$$= \left[m_*^2 \cdot f_2(w)^2\right]\left[1 + \frac{m_u^2}{m_*^2} + 2\frac{m_u}{m_*}\cos\theta\right]$$

$$= [m_*^2 + m_u^2 + 2m_*m_*\cos\theta]f_2(w)^2$$

$$X_u = [m_*^2 + m_u^2 + 2m_*m_*\cos\theta]^2 f_3(w)$$
Then let  $X_u = m_u f_2(w)$ 

Then let

Therefore 
$$m_w = [m_v^2 + m_u^2 + 2m_u m_v \cos \theta]^{1/4}$$

The w scale can be located by the relation

$$\frac{Z}{\ell} = \frac{m_v}{m_u}$$

#### EXAMPLE

$$\frac{1}{u} + \frac{1}{v} = \frac{1}{f}$$
 (lens formula) (Figure 47)

where u = object distance (0 to 100), v = image distance (0 to 80), f = focal distance (0 to 50),

$$X_n = m_n(n); m_n = \frac{n}{100}; X_n = 0.06u$$

where the length of the u scale is 6 in.

$$X_v = m_v(v); \quad m_v = \frac{4}{80}; \quad X_v = 0.05v$$
 where the length of the  $v$  scale is 4 in.

Let  $\theta \Rightarrow 60^{\circ}$ 

$$m_f = (m_u^2 + m_u^2 + 2m_u m_u \cos \theta)^{1/2}$$

$$\sim (0.06^{\circ} + 0.05^{\circ} + 2 \times 0.06 \times 0.05 \times 0.5)^{16}$$

$$\sim (0.0036 + 0.0025 + 0.003)^{16}$$

$$X_f = 0.0955f$$

$$\frac{Z}{\ell} = \frac{0.05}{0.06} = \frac{5}{6} \left( \text{Recall that } \frac{Z}{\ell} = \frac{m_b}{m} \cdot \right)$$

Only one point, such as point 50, need be located on the f scale from the scale equation  $X_f = 0.0955f$  The other points may be projected geometrically. The same is true of the u and v scales

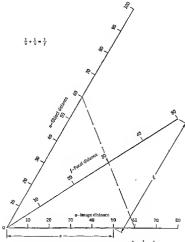


Fig. 47. Alignment Chart for the Relation,  $\frac{1}{u} + \frac{1}{v} = \frac{1}{\hat{f}}$ .

#### SPECIAL CASE 1

If  $m_e = m_u$  and  $\theta = 120^\circ$ ,

$$X_w = m_w f_3(w) = m_w f_3(w)$$

$$\frac{Z}{I} = \frac{m_0}{m} = 1$$

It can be shown easily by geometry that whenever

$$\frac{z}{t} = 1$$

the w scale bisects the angle 0; that is,  $\beta = \theta/2$  (see Figure 48).

$$m_w = [m_u^2 + m_u^2 + 2m_u^2(-\frac{1}{2})]^{56}$$

 $= m_v$ 

Hence the three scales would have the same modulus.

#### EXAMPLE

$$\frac{1}{r_1} + \frac{1}{r_2} = \frac{1}{r}$$
 (Figure 48)

Let  $\tau_1$  and  $\tau_2$  vary from 0 to 10 chms, and r from 0 to 5 chms. If the scale lengths for  $\tau_1$  and  $\tau_2$  are  $2\frac{1}{2}$  in., then

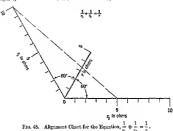
$$m_{r_2} = \frac{25}{10} = 0.25$$

$$m_{r_2} = m_{r_1} = 0.25$$

Therefore, the scale equations are:

$$X_{r_1} \sim 0.25r_1$$
 and  $X_{r_2} = 0.25r_2$ 

Since the angle between the scales is  $120^\circ$ ,  $m_r = m_{r_1} = 0.25$ . Thus the scale equation for the r scale is  $X_r = 0.25r$ . Again, since  $m_{r_2} = m_{r_1}$ , the r scale bisects the angle between the  $r_1$  and  $r_2$  scales. The completed chart is shown in Figure 45.



# SPECIAL CASE 2 have $m_w = [m_u^2 + m_s^2 + 2m_u m_u \cos 90^\circ]^{1/2}$

If  $\theta = 90^{\circ}$ , we have

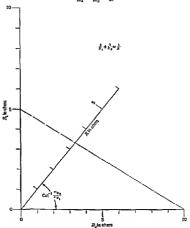
$$m_w = [m_u^2 + m_v^2]^{i_f}$$

$$\frac{Z}{\ell} = \frac{m_v}{m_u} = \cot \beta$$

$$\beta \simeq \cot^{-1}(\frac{m_v}{m_u})$$



$$\frac{1}{R_1} + \frac{1}{R_2} = \frac{1}{R}$$
 (Figure 49)



Fro. 49. Abgument Chart for the Equation,  $\frac{1}{R_1} + \frac{1}{R_1} - \frac{1}{R}$ . Two Scales at Right Angles.

Let R1 and R2 vary from 0 to 10 ohms, and R from 0 to 5 ohms. Suppose that the  $R_1$  scale is 4 in. long; that the  $R_2$  scale is 3 in. long; and that the angle between the scales is 90°. Now

$$m_{\rm P} = \frac{4}{10} = 0.4$$

Furthermore.

$$X_{R_1} = 0.4R_1$$

$$m_{B_4} = \tfrac{3}{10} = 0.3$$

and

$$X_{R_2} = 0.3R_2$$

From the above, it follows that

$$m_R \approx [0.4^2 + 0.3^2]^{1/2} \approx 0.5$$

Therefore

$$X_R = 0.5R$$

The R-scale is located by the ratio  $m_{R_*}/m_{R_*} = 0.3/0.4$ .

#### EXERCISES

73

73. 
$$\frac{1}{u^2} + \frac{2}{s} = \frac{1}{w^3}$$
 where  $u$  varies 0 to 5 and  $v$  varies 0 to 10.

74.

$$\frac{1}{u} + \frac{3}{v^2} = \frac{1}{w}$$

where u varies 0 to 10 and s varies 0 to 2.

## Chapter Seven

## ALIGNMENT CHARTS FOR EQUATIONS OF FOUR OR MORE VARIABLES OF THE FORM

$$f_1(u) + f_2(v) + f_3(w) \cdots = f_4(q)$$

#### EXAMPLE 1

Let us consider the relation

$$u+2v+3w=4t$$

Let 
$$u + 2v = Q$$
 (1)

then 
$$Q + 3w = 4t$$
 (2)

These two equations are of the form discussed in Chapter Three. Suppose (equation 1) that  $m_{\mu} = 1$ ;  $m_{\nu} = \frac{1}{4}$ ; then

$$X_u = u$$
 and  $X_v = \frac{1}{2}(2v) = v$   
 $\frac{m_u}{m_v} = \frac{1}{2} = \frac{2}{1}; \quad m_Q = \frac{1 \times \frac{1}{2}}{1 + \frac{1}{2}} = \frac{1}{3}$ 

Now

If (equation 2)  $m_w = \frac{1}{3}$ ,  $X_w = \frac{1}{3}(3w) = w$ 

$$\frac{m_Q}{m_w} = \frac{\frac{1}{3}}{\frac{1}{3}} = \frac{1}{1}; \quad m_t = \frac{\frac{1}{3} \times \frac{1}{3}}{\frac{1}{3} + \frac{1}{3}} = \frac{\frac{1}{9}}{\frac{9}{3}} = \frac{1}{6}$$

Therefore

 $X_1 = \frac{1}{4}(4\ell) = \frac{2}{4}\ell$ 

From the above calculations, we may now proceed to construct the chart (Figure 50).

Now consider equation 1, u + 2v = Q. Scales u and v are placed u convenient distance apart. Scale u is graduated from its scale equation, Xu = u; and scale v is graduated from its scale equation, Xv ==  $\frac{1}{2}(2v) = v$ . The Q scale is located in accordance with the ratio,  $m_u/m_{\pi}$ =  $1/\frac{1}{2}$  = 2/1. This scale is not graduated.

Now consider equation 2, Q + 3w = 4t. Scale w is placed a convenient distance from the Q scale. Graduations on the w scale are located in accordance with its scale equation,  $X_w = \frac{1}{3}(3w) = w$ . The t scale

is located from the ratio,  $m_Q/m_w=\frac{1}{8}/\frac{1}{3}=1/1$ . The t scale is then graduated from the scale equation,  $X_t=\frac{1}{8}(4t)=\frac{2}{3}t$ .

It should be carefully noted that in most of the practical applications of this form, it is necessary to locate a point on the fourth scale (by a

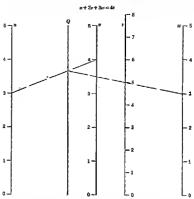


Fig. 50. Afterment Chart for the Equation, u + 2v + 3w = 4t.

computation from the given equation) before graduating that scale. The chart is shown in Figure 50.

### EXAMPLE 2

#### $R = 19.64CJ^2\sqrt{k}$

where R = rate of flow through an orifice, in gallons per minute; C = orifice coefficient (0.6 to 1.5); d = orifice diameter (0.1 to 1.0 in.), and h = head (10 to 100 ft).

Our first step is to write the given equation in type form:

 $\log C + 2 \log d = T$ 

Case a:

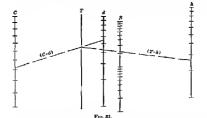
$$\log R - \log 1964 = \log C + 2 \log d + \frac{1}{2} \log h$$

and  $\log R - \log 19.64 = T + \frac{1}{2} \log h$  (2)

(I)

Equations 1 and 2 are now of the form  $f_1(u) + f_2(v) = f_3(u)$ . The nomogram would look like Figure 51.

With this arrangement of scales, it will be observed that the operation of the chart would require, first, a line (isopleth) joining points on



the C and d scales. The intersection of this line with the T scale (dummy or turning axis) would then be joined with a point on the h scale. The intersection of the latter line with the R scale would give the result.

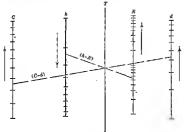
Now let us try a different analysis of the problem. Suppose we write the equations:

Case b: and

$$\log C + 2 \log d = T$$

$$\log R - \log 19.64 - \frac{1}{2} \log h = T$$

Now the arrangement of scales would look like Figure 52. Note: Graduations on the h scale will be directed downwardly, since a minus sign precedes \$ log h.



Fra. 52.

Case c:

A third analysis of the given equation shows that we could write:

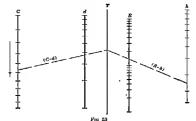
$$\log R - \log 19.64 = T + \frac{2}{3} \log h$$

 $T - \log C = 2 \log d$ 

nnd.

The arrangement of scales in this case would look like Figure 53. Note that this arrangement is much better than the first two, since there is greater clarity in operation and reading.

Having completed the preliminary studies, let us now make the



necessary computations for the final design of the chart which is shown above. Consider equation  $T - \log C = 2 \log d$ .

For scale C

$$m_C = \frac{X_C}{[\log C_n - \log C_0]} = \frac{4 \text{ in.} \pm}{\log 1.6 - \log 0.6} = 9.4 \text{ (use 10.0)}$$

or  $X_C = 10[\log C - \log 0.6]$ , scale equation for C

For scale d

$$m_d = \frac{4 \text{ in. st.}}{2 \log 1.0 - 2 \log 0.1} = 2$$

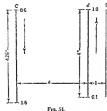
 $X_d = 2[2 \log d - 2 \log 0.1]$ , scale equation for d

Now  $m_d = \frac{m_C \cdot m_T}{m_C + m_T}$ 

or 
$$2 = \frac{10m_T}{10 + m_T}$$

$$m_T = 2.5; \quad \frac{m_C}{m_T} = \frac{10}{2.5} = \frac{4}{1}$$

Sketch layout for  $T = \log C = 2 \log d$  is shown in Figure 54. Now let us consider the equation



 $\log R = \log 19.64 \approx T + \frac{1}{2} \log h$  For scale h

 $m_k =$ 

or 
$$X_h = 15[\frac{1}{2}\log h - \frac{1}{2}\log 10] = 7.5[\log h - \log 10]$$
  
 $\frac{m_T}{m_h} = \frac{2.5}{15} = \frac{1}{6}$ 

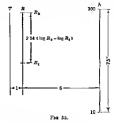
The modulus for the R scale is

$$m_B = \frac{m_T \cdot m_h}{m_T + m_h} = \frac{2.5 \times 15}{2.5 + 15} = 2.14$$

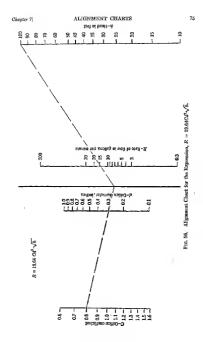
and  $X_R = 2.14[\log R - \log R_I]$ 

where  $R_1$  is a point on the R scale. This point is computed from the original equation.

The sketch layout for  $\log R - \log 19.64 = T + \frac{1}{2} \log h$  is shown in Figure 55. The completed chart is shown in Figure 56.



The designer is cautioned to check the positioning of the R scale in each case, before the adoption of the final form. In seme cases, it will be found that the most desirable form, case e in the above example, may yield one scale whose graduations are not properly oriented with respect to the other scales, that is, one scale may be practically out of reach in spite of the fact that the "length" of the graduated scale is satisfactory.



## Chapter Eight

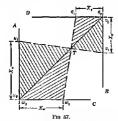
## PROPORTIONAL CHARTS OF THE FORM

$$\frac{f_1(u)}{f_2(v)} = \frac{f_3(w)}{f_4(q)}$$

This equation can be solved in a manner similar to that used in the preceding problem. This simply means transforming the above equation to the form

$$\log f_1(u) - \log f_2(v) = \log f_3(w) - \log f_4(q)$$

In many cases, however, where the functions are linear, the proportional type alignment chart has a distinct advantage in that the scales



are uniform, thus permitting more accurate readings and also simplifying the construction of the scales.

Consider the figure shown in Figure 57.

Scales A and B are parallel to each other, and graduated in accordance with the scale equations;

77

$$X_u = m_u f_1(u)$$
 and  $X_v = m_v f_2(v)$ , respectively

In a similar manner, scales C and D are parallel to each other, and are graduated in accordance with the scale equations:

$$X_w = m_w f_3(w)$$
 and  $X_q = m_q f_4(q)$ 

The angle between scales A and C may be of any convenient magnitude. Triangles  $u_1u_0T$  and  $v_1v_0T$  are similar, hence

$$\frac{X_u}{X_v} = \frac{u_0 T}{v_0 T}$$

Likewise, triangles  $w_0Tw_1$  and  $q_0Tq_1$  are similar, hence

$$\frac{X_{\psi}}{X_{q}} = \frac{w_{0}T}{q_{0}T}$$

But lengths  $u_0T = w_0T$ ; and  $v_0T = q_0T$ . Therefore

$$\frac{X_u}{X_v} = \frac{X_w}{X_g}$$

Or

$$\frac{m_u f_1(u)}{m_v f_2(v)} = \frac{m_u f_3(w)}{m_q f_4(q)}$$

Since

$$\frac{f_1(u)}{f_2(v)} = \frac{f_3(w)}{f_4(q)}$$

it follows that

$$\frac{m_u}{m_v} = \frac{m_w}{m_q}$$

This means that three moduli may be determined from the given data, but the fourth modulus will be dependent upon the first three.

## EXAMPLE 1 (Figure 58)

 $t=\frac{Pd}{2f}$  (thickness of a pipe to withstand internal pressures, where P= pressure (25 to 100 ps)

where f= allowable stress (3000 to 15,000 psi), d= diameter of pipe (10 to 60 in.), and t= thickness of pipe  $(\frac{1}{2}$  to  $\frac{1}{2}$  in.). The given equa-

tion may be put in type form by writing  $\frac{t}{d} = \frac{F}{2f}$ .

$$t = \frac{Pd}{2f}$$

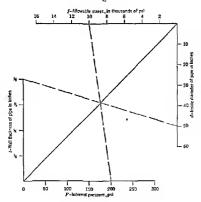


Fig. 58 Proportional Type Chart for the Relation,  $t = \frac{Pd}{2f}$ .

PROPORTIONAL CHARTS

The modulus for P is now computed from  $m_t/m_d = m_n/m_f$ ; or 10/0.1  $= m_p/0.0002$ ;  $m_P = 0.02$  and  $X_P = 0.02P$ . (See Figure 58 for com-

and

pleted chart.)

Chapter 81

Now

 $X_t = 10t$  (scale equation for t)

 $m_d = \frac{5 \text{ in.} \pm}{60} = 0.0833 \text{ (use 0.1)}$ 

and  $X_d = 0.1d$  (scale equation for d)

 $m_f = \frac{5 \text{ in. } \pm 1}{20.000} = 0.000166 \text{ (use 0.0002)}$ 

 $X_f = 0.0002(2f) = 0.0004f$ 

and

Since

#### EXAMPLE 2

$$E = 15(V - v) \left(1 + \frac{w}{10}\right)$$
 (Meyer's evaporation formula) (Figure 59)

where E = the evaporation in inches per month (0 to 10); V = saturated vapor pressure corresponding to monthly mean temperature, t, degrees Fahrenheit, which varies from 30° to 90°; v = the actual vapor pressure; w = the monthly mean wind velocity, mph (0 to 30).

$$v = V \times R.H.$$

where R.H. = the monthly mean relative humidity (30% to 90%) and E = 15V(1 - R.H.)(1 + w/10).

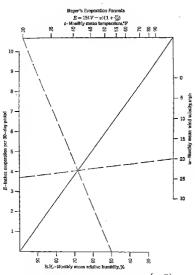
Or 
$$\frac{E}{10 + w} = \frac{1.5(1 - R.H.)}{\frac{1}{4}}$$

where V is a function of t.

$$m_E = \frac{625}{10} = \frac{5}{8}; \quad X_E = \frac{5}{8}E$$

Range of f(t) is 0.164 to 1.408.

$$m_t = \frac{4\frac{1}{2}}{1} = 0.738$$
 (use 0.75);  $X_t = 0.75 \frac{1}{f(t)}$ 



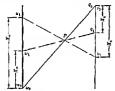
Fro. 59. Meyer's Evaporation Formula,  $B = 15(V - v) \left(1 + \frac{w}{10}\right)$ .

$$m_w = \frac{5}{10 + 30} = \frac{1}{8}; \quad X_w = \frac{1}{8}(10 + w)$$

$$\frac{8}{1} = \frac{m_{\rm H.H.}}{0.75}$$

Therefore 
$$m_{\rm R.H.} = \frac{1.5}{4}$$
;  $X_{\rm R.H.} = \frac{1.5}{4} \times 1.5 (1 - {\rm R.H.}) = \frac{9.0}{1.0} (1 - {\rm R.H.})$   
=  $\frac{4.5}{5} (1 - {\rm R.H.})$ 

The angle between scales A and C (or D and B) need not be 90°. In fact, scale C could coincide with scale A, which means that scale D



Fra. 60.

would coincide with scale B. A study of Figure 60 will reveal that the above statement is true.

$$\frac{X_u}{X_-} = \frac{u_0 P}{P_{\Sigma_0}}$$

$$\frac{X_{\omega}}{X_{\alpha}} = \frac{w_0 P}{P c_0}$$

and since ug = uo and ra = qo.

$$\frac{X_{\bullet}}{X_{\bullet}} = \frac{X_{\bullet}}{X_{\bullet}}$$

Hence, if

$$X_u = m_u f_1(u)$$

$$X_{\nu} = m_{\nu} f_2(v)$$

$$X_w = m_w f_3(w)$$

$$X_a = m_a f_4(q)$$

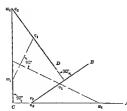
and

$$\frac{f_1(u)}{f_2(v)} = \frac{f_3(v)}{f_4(v)}$$

Variations of the above charts are shown in Figures 61, 62, and 63.



Fro. 62.



Frg. 63,

#### EXERCISES

Hydraulics

75.  $t = \frac{Pd}{2f}$  (required thickness of a pipe to withstand an internal pressure)

where t = thickness in inches (0 to  $\frac{1}{2}$ ); P = internal pressure, pounds per square inch (0 to 100); f = allowable stress, pounds per square inch (0 to 15,000); d = diameter of pipe m inches (0 to 00).

76.  $R = \frac{pel}{\mu}$  (Reynolds number as used for fluid motion [0 to 1,000,000])

where v = velocity, feet per second (0 to 10); l = characteristic dimension $(0 to 2 ft); <math>\mu = coefficient of viscosity, and for water is a function of temperature$ given by the following table:

T	μ
32°F	374 × 10-7
50	273 × 10-7
63	211 × 10-7
80	$167 \times 10^{-7}$
104	$137 \times 10^{-7}$
122	115 × 10 <sup>-7</sup>
140	97.8 × 10 <sup>-7</sup>
158	81.6 × 10 <sup>-7</sup>
176	$74.4 \times 10^{-7}$
191	66 1 × 10 <sup>-7</sup>
212	59.2 × 10 <sup>-7</sup>

 $\rho = \frac{62.4}{22.2} \text{ (for water)}$ 

77.  $Q = C_d \sqrt{2g\hbar}$  (discharge from an orifice or nozzle in cubic feet per second [0 to 20])

where  $c_i =$  coefficient of discharge (0.5 to 1.0); a = area of the orifice (0 to 1.0 sq ft); b = head of water on the orifice (0 to 20 ft), g = 32.2

78.  $r = \frac{1.486}{n} R^{14} S^{14}$  (relocity m as open channel (0 to 30 ft per second) [Manning's formula])

where n = coefficient of roughness (0 000 to 0.035); R = hydraulic radius (0 to 20 ft); S = slope of channel (0 to 0 01).

V = C√RS (Chery formula for velocity in an open channel)
 Ver same limits as in problem 78.

80. 
$$\frac{N_a}{N} = \sqrt{\frac{HP}{H^{34}}}$$
 (formula for a reaction turbine)

where  $N_4$  = specific speed (10 to 100); N = speed in rpm (100 to 2000);  $\Pi P$  = horsenower (to 1000); H = head of water (10 to 200 ft).

#### Strength of Materials

81.  $f = \frac{6M}{6H^2}$  (Stress in the outer fiber of a section of a rectangular beam)

where M = bending moment on the section in inch-pounds (10,000 to 300,000); b = breadth of section, inches (2 to 16); k = depth of section, inches (3 to 20); f = fiber stress, pounds per square inch (750 to 1300).

82. 
$$f = \frac{Mc}{I}$$
 (fiber stress in a beam of any cross section)

where f = fiber stress, pounds per equare inch (3000 to 15,000); M = bending moment on section in inch-pounds (25,000 to 300,000); c = distance from neutral axis where stress is to be found (0 to 10 in.); I = moment of inertia of section (100 to 10,000 in.).

83. 
$$P = 0.196 \frac{d^3}{\pi} f$$
 (load supported by a helical compression spring)

where d = diameter of wire corresponding to B. & S. gage numbers (0000 to 10); r = mean radius of spring (0.5 to 2 in.); f = chearing stress of material (10,000 to 60.000 est).

84. 
$$d = 68.5 \sqrt[3]{\frac{H}{n(T_{max})}}$$
 (required diameter of a shaft in torsion)

where H= horsepower to be transmitted—varies from (0 to 500 hp); n= speed of rotation, rpm (0 to 4000);  $T_{\max}=$  working stress in shear, pounds per square inch (5000 to 15,000); d= diameter (0 to 3 in.).

85. Euler's column formula: 
$$\frac{P}{A} = \frac{C_N^2 E}{\left(\frac{E}{L}\right)^2}$$

where P/A = critical average stress in pounds per square inch, varies from (800 to 20,000), C = fixity coefficient (1 to 4);  $E = \text{modulus of elasticity (1 to$  $30 million psi)}; <math>I_{J/p} = \text{radius of gyration (70 to 200)}$ .

#### Civil

36. 
$$X = \frac{i^2}{6R_cL_c}$$
 (offset from the tangent in a spiral cosement curve, range 0 to 75)

where l= distance in feet from T.S. (point of spiral), range (0 to 600);  $R_c=$  radius of circle in feet (300 to 6000);  $L_c=$  total length of spiral in feet (0 to 600).

87.  $S = \frac{E}{2R_e L_e}$  (the "spiral angle" or total inclination of curve to tancent at any point on a spiral eigenent curve, range, 0° to 30°)

where I = distance in feet from T.S. (point of spiral), range (0 to 600);  $R_c = \text{radius}$  of circle in feet (300 to 6000);  $L_c = \text{total}$  length of spiral in feet (0 to 600),

88. Since  $D = \frac{5729.65}{E_\pi}$  (double-graduate the  $R_\pi$  scale in problem 86 or 87 to read  $D_\pi$  range (\* to 20\*)

89. 
$$e = \frac{gv^2}{32.2R}$$
 (elevation of track in feet)

where g = gauge of track; v = velocity in (cet per second (0 to 60); R = radius of curve in feet (300 to 6000).

90.  $C_0 = \frac{W^2 L^2}{24 L^{12}}$  (correction to a steel tape due to sag [0 to 0.5])

where W = weight of tape in pounds per foot (0 to 0 01); L = length of tape between supports (0 to 100 it), P = applied tension in pounds (0 to 10).

91. 
$$E = 15[V - v] \left[1 + \frac{w}{10}\right]$$
 (Meyer's evaporation formula)

where E is the evaporation in inches per 30-day month (0 to 15 in ).

Make the substitution for r = (R.H) V, where v is the actual raper pressure, R.H, the relative hamidity, and V the vapor pressure at 100% R.H, and v a function of temperature as given in problem 10, functional scales. W is the average wind velocity in miles per hour, varying from (0 to 30) and R.H. is 60% to 90%.

Mechanical

92. HP = 
$$\frac{2\pi LNW}{33,000}$$
 (horsepower as measured by a prony brake [HP, 0 to 75])

where L = length of brake arm in feet (0.5 to 1.5); N = shaft speed, revolutions per minute (0 to 4000); W = load on scales (0 to 200 lb).

93. 
$$\frac{P_1}{P_0} = \left[\frac{V_2}{V_2}\right]^{1.41} \text{ (adiabatic expansion of air)}$$

where  $P_1$  = initial pressure (0 to 300 psi);  $P_2$  = final pressure (0 to 275 psi);  $V_1$  = initial volume (0 to 100 cu ft);  $V_2$  = final volume (0 to 110 cu ft).

94. 
$$M = 0.3155A_1 \sqrt{\frac{P_1}{V_1}}$$
 (discharge from a steam nozzle in a turbine in pounds per second [0 to 6])

where  $A_i = \text{crit}$  area of nearle in square inches (0 to 5);  $P_1 = \text{pressure}$  of steam (15 to 300 ps);  $V_1 = \text{specific volume}$ , cubic fact per pound (0 to 26).

95.  $W = \frac{D \times H^2 \times F}{R}$  (minimum weight of square chimney required

to withstand force of wind [0 to 300,000])

where D = average width of side in feet (0 to 10); H = height of chimney in feet (0 to 100); F = force of wind = 50 for hurricane which is design condition; R = breadth of base in feet (0 to 15), 96. Time required for turning or boring work in the lathe is expressed by

T = L/FN, where T = time in minutes for one cut over the work; L = lengthof cut in inches (6 to 72); N = rpm (10 to 1000); F = feed in inches per revolution (0.002 to 0.30).

97. Time required for planing and shaping is expressed by T = W/FN, where T = time in minutes; W = width of work in inches (3 to 60); F = feed per stroke in inches (0.01 to 0.25); N = number of cutting strokes per minute (2 to 75).

#### Electrical

98.  $\cdot H = \frac{2\pi I r^2}{d^2}$  (field intensity at any point P as shown by the figure)

where I = current in wire in ab-amperes (0 to 500); r = in centimeters (1 to 10); d = in contimeters (1 to 20); H = in lines per square contimeter (0 to 50).



 $R = \frac{p}{100 \text{ Tr}_2}$  (resistance of a wire in ohms [0 to 25]) 99.

where  $l = length of wire in feet (0 to 100); <math>\rho = specific resistance (0 to 1000);$ D = diameter of the wire (0 to 0.1 in.).

100.  $\frac{J}{V} = n_b B_{max}^{1.4} (ergs)$  (bysteresis loss per cubic continueter per cycle in iron)

where  $n_h = \text{constant varying from (0.001 to 0.004) for different types of iron:$ J = hysteresis loss in ergs (or convert to watts since one erg = 10<sup>-7</sup> watt)

(0 to 50 watts); F = volume of iron in cubic centimeters (0 to 1000); B<sub>max</sub> = maximum flux density (0 to 20,000).

101. 
$$\cos \phi = \frac{P}{EI}$$

where  $\phi$  is the phase angle in an alternating current circuit,  $\phi$  varies (0° to 60°); P = power in watts as measured by a wattmeter (0 to 1000); E = voltage of circuit (0 to 250); I = current in amperes (0 to 20).

#### Acronautical

#### 102. $L = 0.00258C_LAV^2$ (lift of an airfeil in pounds [1000 to 20,000]

where  $C_L$  = lift coefficient of autoil section (0 to 2.0); A = area of sirfoll, square feet (100 to 1000); V = velocity in males per hour (50 to 300)

103. 
$$P_{pr} = \frac{550 \pi (\Pi P)}{V}$$
 (propeller throst in pounds [100 to 1000])

where n = propeller efficiency in % varying from (65 to 90%); IIP = engine horsepower (25 to 000); V = velocity of amplane in feet per second (50 to 400).

104. 
$$V = 77.3 \left(n \frac{d}{P}\right)^{14}$$
 (airspeed at level in feet per second [50 to 400])

where n = propeller efficiency (65 to 90%);  $d = W/A_B$ , where W is the weight of the similane and  $A_B$  is the equivalent drag area in square fact; d varies from (150 to 1000); P = W/EP, where HP is the horsepower of the engine, P varies from (1 to 15).

105. 
$$R = \frac{(Kb)^2}{4}$$
 (aspect ratio of a wing, varies [4 to 8])

where K = Monk's span factor for biplanes, for manuplanes K = 1.0, varies from (1 to 1.5); b = span of longest wing in feet (20 to 80), A = total wing area in sequence feet (0 to 1800).

#### Chemical

106. Q = 0 010386 <sup>a</sup>/<sub>k</sub> i (Faraday's law of electrolysis; Q = <sup>m</sup>/<sub>i</sub> is the quantity deposited per second due to electrolysis and varies [0 to 10]) where α = the atomic weight (select a number of elements used in electrolysis).

$$k =$$
 the valence of the element (1 to 4);  $i =$  electric current in amperes (1 to 10).  
107.  $W = \frac{144mP}{1544(1+480)}$  (weight of a gas [0 to 6 lb pr x to ft])

where P = pressure in pounds per square inch absolute (10 to 1000), m = molecular weight (2 to 200); t = temperature (0° to 600°£).

108. W = VNM (titration equation where V milliliters of N normal reagent are required to titrate W grams of a substance, the the million myalent of which is M)

where V = milliliters (10 to 25); N = normal reagent (0.1 to 0.5); M = milli-equivalent (0.02 to 0.20); W = grams of substance (0 to 2.5).

#### General

109. 
$$C = \frac{|V|^2}{e^2}$$
 (centrifugal force acting on a body due to a rotation)

where W = weight in pounds of the body (1 to 150); V = velocity in feet per escend (1 to 50); R = the radius of the path in feet (0.1 to 10); g = 32.2; C = centrifugal force in pounds (0 to 1500).

110. 
$$\frac{u}{v} = \frac{20 + t_2}{20 + t_2}$$

where u varies from 0 to 10; v varies from 0 to 10;  $t_1$  varies from 0 to 100;  $t_2$  varies from 0 to 100.

111.  $(\Delta L) = L \alpha (t_0 - t_0)$ , increase in length of a bar due to temperature changes

where L = length of bar (0 to 100 ft) and  $\alpha = \text{coefficient}$  of expansion as given by the following table:

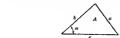
Aluminum = 0.0000244 Hardened steel = 0.000010
Lead = 0.000029 Copper = 0.000017
Wrought fron and mild steel = 0.000019
Grown glass = 0.000009 Tin = 0.000018

 $(t_1 - t_1)$ , change in temperature in degrees Contigrade (0° to 100°)

# 112. I = PRT, (simple interest law)

where I = interest (0 to \$400); P = principal (\$1 to \$1000); R = rate of interest per year period (4 to 8%); 2 = time or period in years (0 to 5 years) (subdivide time scale into months).

113.  $A = \frac{3}{2}\delta c \sin \alpha = \text{area of a triangle shown in the figure}$ 



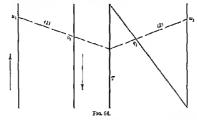
where  $\alpha = (20^{\circ} \text{ to } 100^{\circ})$ ; b = (0 to 10); c = (0 to 10); A = (0 to 50).

## Chapter Nine

## PROPORTIONAL CHARTS OF THE FORM

$$f_1(u) + f_2(v) = \frac{f_3(w)}{f_4(q)}$$

An equation of the above form can be solved by a combination of two types already discussed (Figure 64).



Let

 $f_1(u) + f_2(v) = T$  (1)  $T = \frac{f_2(w)}{f_1(v)}$  (2) (3 parallel scales)

(Z chart)

and or

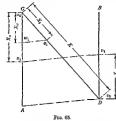
 $f_3(w) = Tf_4(a)$ 

Now let us consider another method for solving the above equation (Figure 65). Suppose that the parallel scales, A and  $B_i$  are graduated in accordance with the scale equations:

$$X_u = m_u f_1(u)$$
  
 $X_v = m_v f_2(v)$ 

and that the scale  $\Lambda$  also carries graduations for the  $f_2(w)$ , the scale equation of which is  $X_w = m_w f_2(w)$ . Let us further suppose that the

diagonal is graduated in accordance with the scale equation  $X_q = m_q f_4(q)$ .



A study of Figure 65 reveals the following relation:

$$\frac{X_u + X_v}{K} = \frac{X_u}{X_\varrho}$$

since triangles CAD and  $Cw_1q_1$  are similar.

Or 
$$\frac{m_{2}T(w) + m_{2}y_{1}}{K} = \frac{m_{2}T_{1}}{m_{2}T_{1}}$$
If  $f_{1}(u) + f_{2}(v) = \frac{f_{2}(v)}{f_{1}(2)}$ 
then  $m_{v} = m_{v}$ 
and  $\frac{m_{v}}{K} = \frac{m_{v}}{m_{v}}$ 
or  $m_{q} = \frac{Km_{v}}{m_{q}}$ 

Hence, to construct an alignment chart of the above form;

(a) Graduate the left side of scale A from its scale equation, X<sub>u</sub> = m<sub>u</sub>f<sub>1</sub>(u).

(Chapter 9

- (b) Graduate scale B from X<sub>v</sub> = m<sub>u</sub>f<sub>2</sub>(v).
  - (c) Graduate the right side of scale A from its scale equation, X<sub>w</sub> ≈ m<sub>w</sub>f<sub>2</sub>(w).
  - $m_{ij}\chi(q)$ .

    (d) Graduate the diagonal scale from  $X_q = m_q f_q(q)$ , where  $m_q = Km_{ij}/m_{ij}$ .

Caution: Do not overlook the fact that point C is the zero value of functions u, w, and q; that point D is the zero value of function v.

#### EXAMPLE

$$V = \frac{\pi h}{a} \left( \frac{5}{4} D^2 + d^2 \right) \text{ (volume of a buoy) (Figure 66)}$$

where h= height of buoy (0 to 10 ft); D= denoter of midsection (0 to 10 ft), d= diameter of base (0 to 10 ft); and V= volume of buoy.

Then

$$\frac{5}{4}D^2 + d^2 = \frac{9V}{\pi h}$$
, which is of the form

$$f_1(u) + f_2(v) = \frac{f_3(v)}{f_4(q)}$$

 $X_D = m_D \frac{5}{4} D^2 = 0.06 \frac{5}{4} D^2 = 0.075 D^2$  (scale length, 7.5 in.)

$$X_d = m_d d^2 \simeq 0.06 d^2$$
 (scale length, 6 in.)

 $X_s = m_s 9V = 0.001 \times 9V = 0.009V$  (scale length approx. 7 in.)

$$\frac{m_V}{m_h} = \frac{m_D}{K}$$

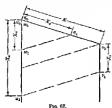
or 
$$m_h = \frac{Km_\pi}{m_D} = \frac{0.001 \times K}{0.66} = \frac{0.1}{6} \frac{30}{\pi}$$

$$=\frac{0.5}{2}$$
, when  $K=\frac{30}{2}=9.55$  in.

$$X_h = m_h \pi h = \frac{0.5}{\pi} \pi h = 0.5h$$

Example: Given; D=8, d=10; h=5. Solution: Join points 8 and 10 on the D and d scale, respectively. Through point 5 on the h scale draw a parallel line. This line cuts the V scale in point V=315. By computation, V=314.29.

If the equation is of the form  $f_1(u) - f_2(v) = f_1(u)/f_0(\eta)$ , positive values of u and v will be laid off in the same direction. This is shown in Figure 67.



114. 0

$$\frac{X_u - X_v}{K} = \frac{X_v}{X_t}$$

Again, if 
$$X_u = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

$$X_w = m_w f_2(w)$$

$$\Lambda_{\mathbf{u}} = m_{\mathbf{u}} j_3(\mathbf{u})$$

$$X_q = m_q f_4(q)$$

$$\frac{m_u}{K} = \frac{m_w}{m_q}$$

Then 
$$f_1(u) - f_2(v) = \frac{f_2(w)}{f_*(v)}$$

## EXAMPLE

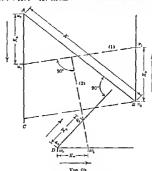
$$u^2 \sim v^2 = \frac{w}{4q}$$
 (Figure 68)

Example: Giren: u = 5; v = 3; q = 4.

Required: w.

Solution. Join points 5 and 3 on the u and v scales, respectively. Through point 4 on the q scale, draw a line parallel to line 1 and read w = 255. By computation, w = 256.

If it is desired to construct a nonogram for an equation of the type form  $f_1(u) + f_2(v) = f_1(w)/f_1(v)$  so that no double scales will be neces-



sary, another arrangement can be made which will overcome this situation.

Let us consider Figure 09. Scales u and w are at right angles. Similarly, scale q and the diagonal AB, which joins the zero values of functions u and u, are at right angles. Scales u and v are parallel.

The geometric relations can easily be determined by studying a typical case. Suppose line 1 joins any two points u<sub>1</sub> and v<sub>2</sub>. Then let us

draw line 2 through point  $w_1$  and perpendicular to line 1. The intersection of line 2 with the q scale will give us point  $q_1$ , the desired solution. Why is this true?

In Figure 69 it will be seen that line BC is parallel to line 1. Again, triangles ABC and  $D_{R}w_{1}$  are similar. Therefore

$$\frac{X_u + X_v}{K} = \frac{X_w}{Y}$$

The remainder of the development is the same as shown previously. There is an advantage in this design over the one which uses parallel in that (1) there is a separate scale for each function and (2) the readings can be made by placing a transparent sized, having but two lines at right angles, over the nomogram. Proper orientation of the lines can be made very quickly.

#### EXERCISES

114.  $A = \frac{d(b_1 + b_2)}{2} \text{ (area of a trapezoid)}$ 



where  $b_1 = \{0 \text{ to } 100\}$ ;  $b_2 = \{0 \text{ to } 99\}$ ;  $d = \{0 \text{ to } 50\}$ ; A = limits corresponding.

115. Weight of a hollow steel tube: 
$$W = \frac{\mathcal{E}_{z}(d^{2} - d_{z}^{2})}{4} \cdot \rho$$

where W = the weight (0 to 100 lb);  $\ell$  = the length in inches (0 to 100); d = the outside diameter (0 to 2 in.);  $d_1$  = the incide diameter (0 to 1.9 in.); p = density = 459.5/1728 lb per cu in.

116. 
$$KV \leftarrow (p_1 + p_2)$$

where  $\Gamma$  is the volume of earthwork per station,  $p_1+p_2$  are average plantages readings in square inches from the cross section drawings, and K is a mornious depending on the length of section and the scale; V=(0 to 1000) in cubic parts  $p_1$  or  $p_2$  (0 to 10), and K= corresponding limits.

 $F = \frac{k}{m}$  (Wall Thickness Sensitivity) 117.

where F is the tensile strength of a metal or alloy, t is the thickness, k and "a" are constants depending on the kind of material. F = (10 to 50 kg per sq mm)

k = constant (10 to 50 kg per so min)

t = (10 to 90 mm)

a = (0.2 to 0.7)

 R = (P = d)t55,000 (strength of a riveted steel plate between. rivet holes)

where P is the pitch of the rivets and d the diameter.

P = (0 to 5 in ) d = (0 to 1 in )

R = (0 to 100,000 lb)

t = (0 to 1 in.)

119.  $\frac{T_d}{T} = e^{rd}$  (ratio of tensions in a rope used over a pulley as shown

in the figure where To is the larger pull)

Ta varies (I to 100 lb)

Ta varies (1 to 100 lb)





## Chapter Ten

# ALIGNMENT CHARTS FOR THE SOLUTION OF EQUATIONS OF THE FORM

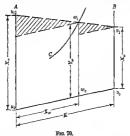
$$f_1(u) + f_2(v) \cdot f_3(w) = f_4(w)$$

Suppose the parallel scales,  $\Lambda$  and B (Figure 70), are graduated in accordance with the scale equations:

$$X_u = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

It is further supposed that a straight line joining points  $u_1$  and  $v_1$  cuts the curved scale, C, in point  $w_1$ , which satisfies the equation.



Points on the scale C are located by co-ordinates,  $X_w$  and  $Y_w$ . Let us develop expressions for  $X_w$  and  $Y_w$ .

From the similar triangles (shaded).

$$\frac{X_u - Y_w}{Y_w - X_v} = \frac{X_w}{K - X_w}$$

from which

$$X_{\mathbf{v}}(K - X_{\mathbf{v}}) + X_{\mathbf{v}}X_{\mathbf{v}} = KY_{\mathbf{v}}$$

$$X_u + X_v \left[ \frac{X_w}{K - X_u} \right] = \left[ \frac{KY_w}{K - X_u} \right]$$

Now

OF

ow 
$$m_u f_1(u) + m_v f_2(v) \left[ \frac{X_u}{K - X_w} \right] \approx \left[ \frac{KY_w}{K - X_w} \right]$$

This is true since  $X_u = m_u f_1(u)$  and  $X_v = m_v f_2(v)$  Careful study of the above equation will show that  $X_w/(K-X_w)$  must equal  $Cf_2(w)$ and that the right-hand member,  $KY_{w}/(K-X_{w})$  must equal  $C_{1}f_{4}(w)$ In order to obtain the equation  $f_1(u) + f_2(v) f_3(w) = f_4(w)$ , it will be seen that  $C = m_u/m_s$  and  $C_1 = m_u$  This means that

$$\frac{X_w}{K - X_u} = \frac{m_u}{m_v} f_2(w) \text{ and } \frac{KY_w}{K - X_u} = m_u f_4(w)$$

$$\frac{X_w}{K - X_u} = \frac{m_u}{m_v} f_3(w)$$

From

$$X_{u} = \frac{K m_{u} f_{3}(w)}{m_{u} f_{3}(w) + m_{u}}$$

and from

from 
$$\frac{KY_w}{K - X_w} = m_u f_4(w)$$

$$Y_w = \frac{Km_w f_4(w) - X_w m_w f_4(w)}{K}$$

$$m_w f_2(w) m_w f_4(w)$$

OF

$$Y_w = m_w f_4(w) - \frac{m_w f_3(w) m_w f_4(w)}{m_w f_3(w) + m_v}$$

$$Y_w = \frac{m_u m_v f_4(w)}{m_v f_3(w) + m_v}$$

Hence, to construct an alignment chart of the above form, (1) Graduate the A and B scales from their scale equations;

$$X_{\Psi} = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

(2) Locate the curved scale by its co-ordinates:

$$X_{w} = \frac{Km_{w}f_{3}(w)}{m_{w}f_{3}(w) + m_{w}}$$

$$Y_{w} = \frac{m_{w}m_{w}f_{4}(w)}{m_{w}f_{4}(w) + m_{w}}$$

Caution. The axis from which distances  $Y_w$  are laid off is the line which joins the zero value of function,  $f_1(u)$ , with the zero value of function,  $f_2(v)$ .

## EXAMPLE

 $w^2 + pw + q = 0$  (quadratic formula)

Transposing

$$q + pw = -w^2$$

which is of the form

$$f_1(u) + f_2(v) \cdot f_3(w) = f_4(w)$$

$$X_q = m_q q = 0.6q$$

$$X_n = m_n n = 0.6n$$

where  $m_q$  and  $m_q$  were arbitrarily chosen as 6.6.

$$X_w = \frac{Km_u f_3(w)}{m_u f_3(w) + m_v}$$

If 
$$K = 5$$
 in.

$$X_{w} = \frac{5 \times 0.6 \times w}{0.6w + 0.6} = \frac{5w}{w + 1}$$

$$Y_{w} = \frac{m_{w}m_{w}f_{d}(w)}{m_{w}f_{d}(w) + m_{w}}$$

$$= \frac{0.6 \times 0.6(-w^2)}{0.6w + 0.6} = \frac{-0.6w^2}{w + 1}$$

See Figure 71 for graphical solution.

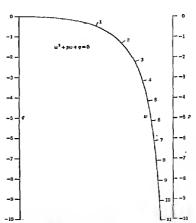


Fig. 71. Alignment Chart for the Equation,  $w^2 + pw + q = 0$ .

#### EXERCISES

## 120. $O = 3.23(B - 0.2H)H^{32}$ (Francis formula for the quantity of water flowing over a contracted weir)

where B = width of the weir in feet (0 to 5);  $H = \text{head over the crest (0 to$ 5 ft); Q = calculate limits.

S = Vnt - \(\frac{1}{2}\sigma^2\) (distance traveled by a body projected upward)

with a velocity va. after a time. th where E = distance in feet (calculate limits);  $v_e = \text{velocity}$  in feet per second

(0 to 100):  $t \approx time in seconds (0 to 5): and <math>\sigma = 32.2$ .

122.  $\left(\frac{I}{V}\right) = 0.0982 \left(\frac{D^4 - d^4}{D}\right)$  (section modulus of a hollow tube se outside and inside diameters are D and d, respectively)

where D varies (0 to 10 in.) and d varies (0 to 9 in.).

123.  $V = 0.649 \frac{T}{\pi} - \frac{22.58}{\pi^{32}}$  (specific volume in cubic feet of super-

heated eteam under a pressure of p pounds per square inch and with a temperature, T, in degrees Fahrenheit)

where T varies (250 to 600): n = (30 to 200).

V = ½πτ²h + ½πλ² (volume of a spherical segment with one base)

where h is the altitude of the segment and r the radius of the sphere. r various (0 to 10 in.) and & varies (0 to 10 in.).

# Chapter Eleven

## MISCELLANEOUS FORMS

1. 
$$\frac{I_1(u) + I_2(v)}{I_1(u) - I_2(v)} = \frac{I_3(u)}{I_1(d)}$$
 (Figure 72)

$$X_u = m_u f_t(u)$$
  $X_w = m_w f_3(w)$ 

$$X_{v} = m_{v}f_{3}(v)$$
  $X_{g} = m_{2}f_{4}(q)$ 

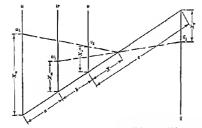


Fig. 72. Chart for an Equation of the Form,  $\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_2(u)}{f_2(v)}$ 

From similar triangles.

$$\frac{X_u}{X_u} = \frac{a+b+X}{X}$$

$$\frac{X_w}{X_q} = \frac{b+X}{c-X}$$

Eliminating X.

$$\frac{X_w}{X_w} = \frac{b + \frac{a+b}{X_w}}{\frac{x}{X_w} - 1}$$

$$\frac{c - \frac{a+b}{X_w} - 1}{\frac{x}{X_w} - 1}$$

and simplifying,

$$\frac{X_u}{X_q} = \frac{bX_u + aX_q}{cX_u - (a+b+c)X_q}$$

then

$$\frac{f_3(w)}{f_4(q)} = \frac{bm_w f_1(u) + am_v f_2(v)}{cm_w f_1(u) - (a+b+c)m_w f_2(v)}$$

If

$$b = \frac{m_v}{m_v} \cdot a, \quad a + b + c = c \frac{m_u}{m_v}$$
is  $am_v$ 

and

$$\frac{m_w}{m_q} = \frac{am_v}{cm_u}$$

it can be shown that

$$\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_3(w)}{f_4(q)}$$

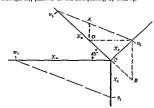
By algebraic manipulation of the three previous substitutions,

$$\frac{m_u + m_v}{m_u - m_v} = \frac{m_q}{m_w}$$

$$\frac{a}{b} = \frac{m_{\pi}}{m_{\pi}}$$

$$\frac{a+b+c}{c} = \frac{m_a}{m_b} \text{ (Intermediate steps are left to the reader)}$$

2. The type form discussed above out be represented by an alignment chart of the design shown in Figure 73. The scales for f<sub>1</sub>(v) and f<sub>2</sub>(v) and f<sub>2</sub>(v) and f<sub>3</sub>(v) are at right angles; piles with the scales for f<sub>4</sub>(v) and f<sub>4</sub>(v) are at right angles; and a 48° angle exists between the f<sub>1</sub>(v) and f<sub>4</sub>(v) scales. If values u<sub>1</sub>, v<sub>1</sub>, and u<sub>2</sub> are selected, the values of c<sub>1</sub> is obtained by drawing a line through w<sub>1</sub>, parallel to the line joining s<sub>1</sub> with v<sub>2</sub>.



F10. 73 Alternate Form of Chart for the Equation in Fig. 72.

Let us examine the geometry of the figure. Tripngles  $u_1v_1B$  and  $u_1AO$  are similar (from the construction shown). Therefore,

$$\frac{v_1C + CB}{v_1O} = \frac{v_1B}{AO}$$

άī

$$\frac{X_u + X_v}{X_u - X_v} = \frac{v_t B}{AO}$$

Also, triangles AOv1 and w1Cq1 are similar. Hence,

$$\frac{Ov_1}{AO} = \frac{X_{\omega}}{Y}$$

Sinco

$$Ov_1 = v_1 B$$

$$\frac{X_u + X_v}{X_v - X_v} = \frac{X_v}{X_v}$$

$$X_{\mathbf{u}} = m_{\mathbf{u}} f_1(\mathbf{u})$$

$$X_v = m_v f_2(v)$$

$$X_w = m_w f_3(w)$$

$$X_a = m_a f_A(a)$$

$$\frac{m_w f_1(u) + m_w f_2(v)}{m_w f_1(u) - m_w f_2(v)} = \frac{m_w f_3(w)}{m_w f_4(\sigma)}$$

This means that  $m_u = m_v$  and  $m_w = m_q$  if

$$\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_3(w)}{f_4(a)}$$

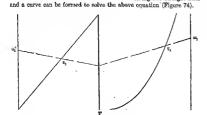
3.  $f_1(u) \cdot f_2(v) + f_3(w) \cdot f_4(q) = f_5(q)$ 

Let

$$f_2(u) \cdot f_2(v) = T$$

$$T + f_2(w) \cdot f_4(q) = f_8(q)$$
 (2)

Thus a combination of a Z chart and one involving two straight lines



Fro. 74. Alignment Chart for an Equation of the Ferm,  $f_1(u) \cdot f_2(v) + f_3(w) \cdot f_4(q) = f_3(q)$ .

2. The type form discussed above one be represented by an alignment chart of the design abova in Figure 73. The scales for f<sub>1</sub>(v) and f<sub>2</sub>(v) and f<sub>2</sub>(v) are at right angles; allowing, the scales for f<sub>2</sub>(v) and f<sub>3</sub>(v) are at right angles; and a 48° angle exists between the f<sub>1</sub>(v) and f<sub>2</sub>(v) scales. If values u<sub>1</sub>, v<sub>3</sub>, and u<sub>2</sub> are selected, the value of c<sub>1</sub> is obtained by drawing a fine through u<sub>2</sub>, parallel to the line joining u<sub>3</sub> with v<sub>4</sub>.

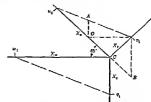


Fig. 73. Alternate Form of Chart for the Equation in Fig. 72.

Let us examine the geometry of the figure. Triangles  $u_1v_1B$  and  $u_1AO$  are similar (from the construction shown). Therefore,

$$\frac{u_tC + CB}{u_tO} = \frac{v_tB}{AO}$$

or

$$\frac{X_n + X_n}{X_n - X_n} = \frac{v_1 B}{A O}$$

Also, triangles AOv, and w.Co, are similar. Hence,

$$\frac{Ov_1}{4O} = \frac{X_w}{Y}$$

Since

$$0v_1 = v_1B$$

$$\frac{X_u + X_v}{X_u - X_v} = \frac{X_w}{X_v}$$

 $X_u = m_u f_1(u)$ 

$$X_v = m_v f_2(v)$$

$$X_w = m_w f_3(w)$$

$$X_q = m_q f_4(q)$$

then

$$\frac{m_u f_1(u) + m_v f_2(v)}{m_u f_1(u) - m_v f_2(v)} = \frac{m_u f_3(w)}{m_u f_4(q)}$$

This means that  $m_u = m_p$  and  $m_w = m_q$  if

$$\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_3(w)}{f_4(q)}$$

# 3. $f_1(u) \cdot f_2(v) + f_3(w) \cdot f_4(q) \approx f_5(q)$

Let

$$f_1(u) \cdot f_2(v) = T$$

and

$$T + f_3(w) \cdot f_4(q) = f_5(q)$$
 (2)

...

Thus a combination of a Z chart and one involving two straight lines and a curve can be formed to solve the above equation (Figure 74).

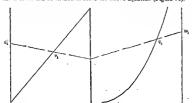


Fig. 74. Alignment Chart for an Equation of the Form,  $f_1(u) \cdot f_2(v) + f_3(w) \cdot f_4(q) = f_0(q)$ .

4.  $f_1(u) + f_2(v) \cdot f_3(w) = f_4(q)$  (Figure 75)

Let

 $f_2(v) \cdot f_3(w) = T$  $f_1(u) + T = f_4(q)$ and

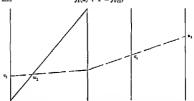


Fig 75 Alignment Chart for an Equation of the Form,  $f_2(u) + f_2(v) \cdot f_3(u) = f_4(v)$ 

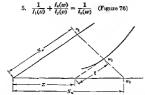


Fig. 76. Alignment Chart for an Equation of the Form,  $\frac{1}{f_1(u)} + \frac{f_1(u)}{f_2(v)} = \frac{1}{f_2(u)}$ .

$$X_u = m_u f_1(u)$$
  $Z = m_u f_3(w)$ 

$$X_v = m_v f_2(v)$$
  $I = m_v f_3(w) f_4(w)$ 

Points on the curve are located from

$$Z = m_n f_3(w)$$

$$Z = m_n f_3(w)$$

 $I = m_* f_2(w) f_4(w)$ and

# in the following manner:

- Graduate a temporary w scale along the horizontal scale for f<sub>1</sub>(u). 2. Draw lines through points on the temporary w scale, parallel to the r sesle.
- On these lines lay off distances obtained from l = m<sub>v</sub>f<sub>2</sub>(w)f<sub>4</sub>(w). using the same value of w through which the parallels were drawn.

## 6. $f_1(u) \cdot f_2(v) \cdot f_3(w) = f_4(q) \cdot f_6(r)$ (Figure 77)

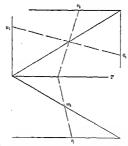


Fig. 77. Combination Proportional and Z Churt for an Equation of the Form,  $f_1(u) \cdot f_2(v) \cdot f_3(w) = f_4(q) \cdot f_6(r)$ .

Let (proportional chart) (1)

and

and 
$$\frac{f_5(r)}{T} \simeq \frac{f_3(w)}{1}$$
 (2)

or 
$$f_5(r) = Qf_3(w)$$
 (Z chart)

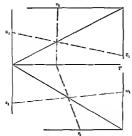
Note: An alternate form could be developed by expressing the given equation logarithmically, resulting in an abgriment chart having parallel scales

7. 
$$I_1(u) I_2(v) \cdot I_3(w) = I_4(q) \cdot I_5(r) \cdot I_6(s)$$
 (Figure 78)

 $\frac{f_1(u)}{f_2(v)} = \frac{T}{f_2(v)}$ Let (1)

$$\frac{f_6(r)}{T} = \frac{f_3(w)}{f_6(s)} \tag{2}$$

(2)



Pro. 78. Combination Proportional Charts for an Equation of the Form,  $f_1(u) \cdot f_2(v) \ f_3(w) = f_4(q) \cdot f_4(r) \cdot f_4(x)$ 

#### DESIGN OF NET CHARTS

Problems involving four variables may also be solved by a net chart which makes it possible to read all four variables with one isopleth. The principles involved in the design of this type chart are the same as those employed in the design of a chart of the form,  $f_1(u) + f_2(v) =$  $f_3(w)$ .

#### RXAMPLE

Suppose the given equation is  $S = V_0t + \frac{1}{2}at^2$ , where S = distancetraversed in feet (9 to 15),  $V_0$  = initial velocity in feet per second (0 to a = acceleration in feet per second<sup>2</sup> (0 to 4), and t = time interval in seconds (1 to 4).

Solution. Let t = 1, 2, 3, and 4. With these values for t, the following equations result, namely:

$$S = V_0 + \frac{a}{2} \tag{1}$$

$$S = 2V_0 + 2a \tag{2}$$

$$S = 3V_0 + \frac{3}{2}a$$
 (3)  
 $S = 4V_0 + 8a$  (4)

$$S = 4V_0 + 8a \tag{4}$$

All the above equations are of the form  $f_1(u) + f_2(v) = f_3(w)$ .

Consider the first equation,  $S = V_0 + a/2$ . It may be written  $V_0 - S = -a/2$  to conform with the type equation  $f_1(u) + f_2(v) =$ f2(w). Suppose that the desired length of the Vo and S scales is 10 units; then, the scale equations are:

$$X_{\mathbf{r}_0} = V_{\mathbf{0}}$$
 and  $X_{\mathbf{c}} = \frac{2}{3} \mathbf{S}$ .

From the above moduli, the modulus for the a scale is  $\frac{1 \times \frac{9}{3}}{1 + 2} = \frac{2}{2}$ ; and its position is determined from the ratio  $\frac{1}{2} = \frac{3}{2}$ . The scale equation

for a then becomes  $X_a = \frac{9}{5}(a/2) = a/5$ . The chart for the equation  $V_0 - S = -a/2$  is shown in Figure 79.

Now, consider equation 2,  $S = 2V_0 + 2a$ . This equation can be rewritten in type form as  $2V_0 - S = -2a$ .

If we are to use the same  $V_0$  and S scales as shown in Figure 79, the effective moduli for the scale equations,  $X_{v_0} = m_{v_0}(2V_0)$  and  $X_s = m_4S$ , must be the same as those used in equation 1.

This means that  $m_v$  must equal  $\frac{1}{2}$  in order for the effective modulus

...

to equal one. Therefore, the scale equation for  $V_0$  in equation 2 is  $X_{v_0} = \frac{1}{2}(2V_0) = V_0$ .

Since the coefficient of S is the same in both equations 1 and 2, no change in modulus for the S scale is necessary. Note, however, that

the location of the a scale is determined by the ratio  $\frac{m_{0a}}{m_{a}}$  =

The chart for equation 2 is shown in Figure 80.

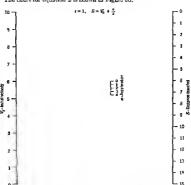
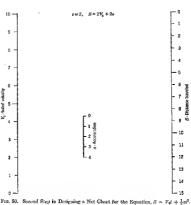


Fig. 79. First Step in Designing a Net Chart for the Equation,  $S = V_{sl} + \frac{1}{2}al^2$ .



If the two charts are superposed, the resulting chart, Figure 81, would be obtained.

It should be clear that similar calculations for equations 3 and 4 would be necessary to complete the net chart. It is not necessary to

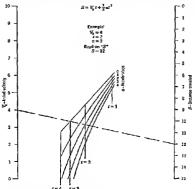


Fig. 81. Net Chart for the Equation,  $S = V_{cl} + \frac{1}{2}cl^2$ .

make separate charts for each of the four equations, since the V<sub>2</sub> and S scales are the same in all cases. Calculations for positioning the a scale are necessary and, in addition, the moduli for the a scale set and the computed in order to graduate those scales property. Finally, curves drawn through his values of a will establish the net for the variable, a. The net for the variable, 4, consists of the vertical lines which first carried the values of a when qualted 1, 2, 3, and 4. The completed chart is shown in Figure S1.

## EXERCISES

125.

f = 9W

when f = fiber stress (500 to 2500 psi); l = length of wooden beam (5 to 30 ft); W = total load (1000 to 12,000 lb); b = width of beam (2 to 12 in.); d = depth of beam (4 to 16 in.).

126.

 $\Delta_{max} = \frac{Pl^3}{48EI}$ 

where  $\Delta =$  deflection of  $\pi$  simple beam with a concentrated load at the center, in inches; P = concentrated load (500 to 10,000 lb); I = length of beam (60 to 300 ln); E = modulus of elasticity (2 × 10° to 30 × 10° psi); I = moment of inertia (1009 to 20,000 in.)

127.

 $\Delta_{max} = \frac{WP}{KKT}$ 

where A is deflection in inches of simple beams leaded as follows: (a) uniformly (K=384/5), (b) load increasing uniformly to one and (K=1000/13), (c) load increasing uniformly to one and (K=60); W= total load (10,000 to 300,000 lb); E and I as above; and I=(120 to 600 in.).

### SUMMARY OF TYPE FORMS

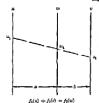
1. 
$$I_1(u) + I_2(v) = I_3(w)$$

Scale equations:

$$X_u = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

$$X_w = \frac{m_u m_u}{m_u + m_u} f_3(w)$$



$$\frac{a}{b} = \frac{m_u}{m_v}$$

2. 
$$f_1(u) = f_2(v) \cdot f_d(w)$$

Scale equations:  

$$X_u = m_u f_1(u)$$

$$X_v = m_v f_2(v)$$

$$X_{\omega} = \frac{K}{K_1 j_3(\omega) + 1}$$

where  $K_1 = \frac{m_u}{m_d}$  and K is the length of the diagonal,



$$f_1(u) = f_2(v) \cdot f_2(w)$$

3. Scale equations:  $f_1(u) + f_2(v) = \frac{f_1(u)}{f_2(w)}$ 

 $X_u = m_u f_1(u)$ 

 $X_v = m_v f_2(v)$ 

 $m_u = m_v$ 

 $X_w = Kf_3(w)$ 



or

Scale equations:

$$\frac{1}{I_1(u)} + \frac{1}{I_2(v)} = \frac{1}{I_2(w)}$$

$$X_u = m_u f_1(u)$$

 $X_v = m_e f_2(v)$ Location of 10 scale:

$$\frac{Z}{z} = \frac{m_z}{z}$$

Graduate to scale by

(a) 
$$Z = m_v f_3(w)$$
 and parallels to  $u$  scale,

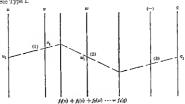
(b)  $X_w = [m_*^2 + m_u^2 + 2m_u m_* \cos \theta]^{H_*} f_8(w)$ 

$$\frac{1}{f_i(u)} + \frac{1}{f_i(v)} = \frac{1}{f_i(w)}$$

5.

$$f_1(u) + f_2(v) + f_3(w) \cdots = f_4(q)$$

Sec Type 1.



6.

$$f_1(v) + f_2(v) + f_3(w) + \cdots = \frac{f_1(u)}{f_2(v)} = \frac{f_3(w)}{f_4(q)}$$

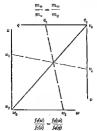
Scale equations:

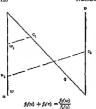
$$X_u = m_u f_1(u)$$

$$X_w = m_w f_3(w)$$

$$X_v = m_v f_2(v) \hspace{1cm} X_q = m_q f_4(\underline{q})$$

and





7. 
$$f_1(u) + f_2(v) = \frac{f_3(w)}{f_4(q)}$$

Scale equations:

$$X_u = m_u f_1(u)$$

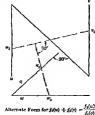
$$X_v = m_v f_2(v)$$
  
 $X_w = m_w f_3(w)$ 

$$A_{so} = m_{so/3}(t)$$

$$X_q = m_q f_4(q)$$
 where  $m_q = \frac{Km_w}{m_u}$ 

8. 
$$f_1(u) + f_2(v) = \frac{f_2(w)}{f_4(g)}$$

Same as in 7. Alternate form of chart shown below.



Scale equations:

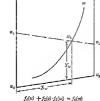
 $X_n = m_n f_1(u)$ 

$$X_v = n \iota_v f_2(v)$$

$$X_w = \frac{Km_w f_0(w)}{m_w f_0(w) + m_v}$$

$$m_v f_{\delta}(w)$$

$$u = \frac{m_u m_u f_d(w)}{m_u f_d(w) + m_u}$$



## Chapter Twelve

# PRACTICAL SHORT-CUTS IN THE DESIGN OF ALIGNMENT CHARTS

If the designer is thoroughly grounded in the theory of alignment charts and fully understands the mathematical methods employed in changing a given equation to a type form, it is frequently possible to short-cut the actual construction of the chart.

#### EXAMPLE 1

Suppose that the given equation is  $M = w\xi^2/8$  (bending moment in foot-pounds), where the ranges are w (10 to 300 lb per ft) and ! (5 to 30 ft).

If a chart consisting of parallel scales is desired, the designer recognizes the fact that the equation can be converted to the form:

$$\log v + 2\log l = \log M + \log 8$$

The chart can now be constructed without making any further calculations. The following procedure is suggested:

- 1. Draw two parallel lines any convenient distance apart.
- 2. Graduate the left-hand scale for w by simply marking the lower point 10 and the upper point 300. Other points on the scale may be located by projecting from a log scale (two-deck slide rule scale or commercial log sheets having two decks).
- 3. Mark the lower point of the 1 scale 5 and the upper point 30. Again, locate additional graduations by projecting from a log scale.
- 4. Now calculate two points for M, i.e.:
- (a) Let w = 40 and l = 10. This yields M = 500.
- (b) Let w = 160 and l = 5. This yields M = 500.

The point in which the line joining 40 and 10 intersects the line joining 160 and 5 is point M = 500. The vertical line through this point locates the M scale. A second point on this scale can be now located 122

by letting w=40 and l=30, which yield M=4500. The line joining w=40 with l=30, then cuts the M scale in point 4500. Other points may be obtained by projecting from a log scale. The completed chart is shown in Figure 82.

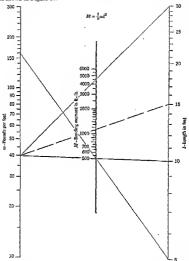


Fig. S2. Alignment Chart for the Equation,  $M = \frac{1}{2} n \vec{r}$ , Constructed by the Short-Cut Method.

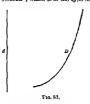
#### EXAMPLE 2

Consider the equation,

$$S = 0.0982 \left( \frac{D^4 - d^4}{D} \right)$$
 (section modulus for tubes and bars)

where D and d = (0 to 10 in.) and  $S = (0 \text{ to } 100 \text{ in.}^2)$ .

The equation may be converted to the form,  $0.0982d^4 + DS = 0.0982D^4$ , which is in the type form,  $f_1(u) + f_2(v) \cdot f_3(u) = f_4(u)$ .



The chart will consist of two parallel scales for d and S respectively, and a curved scale for D A preliminary sketch of the chart would look something like Figure 83.

The following procedure is sug-

gested:

1. Draw the d and S scales a

convenient distance apart.

2. Mark the lower point on the

Mark the lower point on the d scale, 0 and the upper point 10.

 Likawise, mark the lower and upper points on the S scale
 and 100, respectively. Since

the function of S is linear, this scale will be uniform and can be reachly graduated.

readily graduated. 4. The d scale can be graduated by first laying out a  $d^4$  scale and then projecting this scale to the d scale.

5. If S=0, then  $d^*=D^*$ . Draw lines through S=0 and points on the d scale. Somewhere on these lines will be found the corresponding values of D.

Now let d = 0; then DS = 0.0982D<sup>4</sup>. From this equation, we can
determine values of S for given values of D.

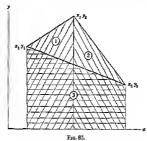
D	5	6	7	8	9	10
E	12.3	21.2	33.7	50,3	71.6	98.2

Now draw lines through d = 0, and the values of S shown in the table above.

# Chapter Thirteen

# THE USE OF DETERMINANTS IN THE DESIGN AND CONSTRUCTION OF ALIGNMENT CHARTS

Most students find the geometric method discussed in the previous chapters a simple and direct approach to the design and construction of abgnment charts. It is felt, however, that an introduction to the method which employs determinants is desirable so that students will be enabled



to comprehend, more fully, treatments based on determinants exclusively.

Let us consider Figure 85. The area of the triangle may be obtained by the difference between the area of transgood 3 and the sum of the areas of trapezoids 1 and 2; or

Area of triangle

$$= \frac{1}{2}[(y_2 + y_1)(x_2 - x_1) + (y_2 + y_3)(x_3 - x_2) - (y_1 + y_3)(x_2 - x_1)]$$

In determinant form this would be

$$A = \frac{1}{2} \begin{bmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_2 & y_3 & 1 \end{bmatrix}$$

If point  $x_2y_2$  were placed on the line joining  $x_1y_1$  with  $x_2y_3$ , the points are said to be co-linear, or the area of the triangle is zero. Hence

$$A = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = 0$$

$$\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_2 & y_2 & 1 \end{vmatrix} = 0$$

or when

the points  $x_1y_1$ ,  $x_2y_3$ , and  $x_3y_3$  are on the same line.

### EXAMPLE 1

Suppose we have the determinant

$$\begin{vmatrix} 0 & u & 1 \\ 1 & v & 1 \\ \frac{1}{2} & \frac{w}{2} & 1 \end{vmatrix} = 0$$

- What does the determinant mean?
- How can we construct an alignment chart from this determinant? In order to answer the first question, we must learn how to expand, or evaluate, the determinant, which is done in the following manner:



- (a) Multiply 0, v, and 1. This is step 1 (see arrow).
- (b) Multiply 1, w/2, and 1. This is step 2 (see arrow).

- (c) Multiply 1, 1, and u. This is step 3 (see arrow).
- (d) Add the results of steps (a), (b), and (c). Thus far we have:

$$\left[0+\frac{w}{2}+\frac{u}{2}\right]$$

Now start in the upper right-hand corner.

- (e) Multiply 1, v, and 2. This is step 4 (see arrow).
- (f) Multiply 1, w/2, and 0. This is step 5 (see arrow).
- (g) Multiply 1, 1, and u. This is step 6 (see arrow).
- (h) Add the results of steps c, f, and g. This is

$$\left[\frac{v}{2}+0+u\right]$$

Finally, subtract h from d, i.e.,

or

$$\frac{w}{2}+\frac{v}{2}-\frac{v}{2}-u=0$$

Now with regard to the second question. If we consider 0, u as  $x_1y_1$ ; 1, v as  $x_2y_3$ ; and  $\frac{1}{2}$ , w/2 as  $x_3y_3$ , we may plot points for u, v, and w by assigning definite values such as 0, 1, 2, 3 · · · n to each.

Since the  $\pi$  value is zero for all values of u, all points of u will lie on the Y axis. Likewise, since  $\gamma_2 = 1$ , all points of v will lie on all perillel to the Y axis and one unit to the right. Similarly,  $z_2 = \frac{1}{2}$ , and all points of v will lie on a line parallel to the Y axis and a  $\frac{1}{2}$  unit to the right. It should be observed that since  $y_2 = w_2^2$ , the distance between consecutive values of v will be half the distance between consecutive values of v or v.

A straight line which joins a point on the u scale with one on the v scale will cut the w scale in a value which satisfies the equation u + v = w (Figure 86). While the above material is easy to follow, one may wonder how the determinant

$$\begin{vmatrix} 0 & u & 1 \\ 1 & v & 1 \\ \frac{5}{2} & \frac{w}{2} & 1 \end{vmatrix} = 0$$

was developed in the first place. This could have been done by trial

and error, observing that the right-hand column must consist of ones, and that only one variable should appear in each row.

- A better approach, one which is direct and mathematically correct, is this:
  - (a) First, write the equation u + v − w = 0.

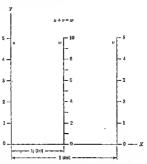


Fig. 85. Chart for the Equation, u + v = w, Constructed by the Method of Determinants.

- (b) Second, let x = u, and y = s.
   (c) Third, write the expressions
- (c) 1 mrd, write the expression

$$x-u=0$$

$$y \rightarrow v = 0$$

$$x+y-w=0$$

It should be noted that we now have three equations in x and y. If they are consistent, the determinant made up from the coefficients of x and y and the constant term must vanish. [See Bocher's text Introduction to Higher Algebra (Chapter Four).] This means that

$$\begin{vmatrix} 1 & 0 & -u \\ 0 & 1 & -v \end{vmatrix} = 0$$

The value of this determinant is u + v = w. You will recall that the determinant must be in the form

$$\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_1 & y_2 & 1 \end{vmatrix} = 0$$

before the chart can be constructed. How can we manipulate the determinant in order to transform it to the form.

$$\begin{vmatrix} 0 & u & 1 \\ 1 & v & 1 \\ \frac{1}{2} & \frac{w}{2} & 1 \end{vmatrix} = 0$$

Let us start with

$$\begin{vmatrix} 1 & 0 & -u \\ 0 & 1 & -v \\ 1 & 1 & -w \end{vmatrix} = 0$$

Column 1 may be replaced by the sum of columns 1 and 2, yielding

$$\begin{vmatrix} 1 & 0 & u \\ 1 & 1 & v \end{vmatrix} = 0$$
 (Note column 3 above was multiplied by  $-1$ .)

Now the bottom row may be divided by 2, resulting in

$$\begin{vmatrix} 1 & 0 & u \\ 1 & 1 & v \\ 1 & \frac{1}{2} & \frac{w}{2} \end{vmatrix} = 0$$

By interchanging columns we get,

$$\begin{vmatrix} 0 & u & 1 \\ 1 & v & 1 \\ \frac{1}{2} & \frac{w}{2} & 1 \end{vmatrix} = 0$$

which is known as the "design determinant." All the steps shown above are permissible when the value of the determinant is zero. Rules for operating determinants are available in any good algebra textbook.

## EXAMPLE 2

Given:  $u + vw = w^2$ 

Required: The design determinant. Solution: Let x = u and y = v.

Now

$$x - u = 0 \tag{1}$$

$$y - v = 0$$
 (2)  

$$x + yw - w^2 = 0$$
 (3)

If these equations are consistent, then

$$\begin{vmatrix} 1 & 0 & -u \\ 0 & 1 & -v \\ 1 & m & -m^2 \end{vmatrix} = 0$$

Replace column one by the sum of the first two columns.

$$\begin{bmatrix} 1 & 0 & u \\ 1 & 1 & v \\ w + 1 & w & w^2 \end{bmatrix} = 0$$

Divide the bottom row by w + 1.

$$\begin{vmatrix} 1 & 0 & u \\ 1 & 1 & v \\ 1 & \frac{w}{w+1} & \frac{w^2}{w+1} \end{vmatrix} = 0$$

Rearrange the columns

Construct the chart from the above determinant (Figure 87).

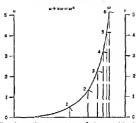


Fig. 87. Chart for the Equation,  $u+vv=w^2$ , Constructed by the Method of Determinants.

Points on the w scale can be plotted from the following co-ordinates:

	107	0	1	2	3	4	5
2-00-ordinate	$\frac{v}{v+1}$	0	1	3	*	9	3
y-co-ordinate:	w <sup>1</sup> w + 1	0	1/2	4	4	12°	꺚

Up to this point no mention has been made of scale moduli. In practical abgument charts this is a significant consideration.

#### EXAMPLE 3

Suppose we consider the equation u + v = w again. Let us assume that u varies from 2 to 10 and that v varies from 5 to 15. You will recall that we had written the expressions,

$$x - u = 0$$

$$y - v = 0$$

$$x + y \sim w = 0$$

Now, however, let us introduce the scale moduli by writing

$$x - m_u u = 0$$
  
 $y - m_v v = 0$ 

and 
$$\frac{x}{m_u} + \frac{y}{m_v} - w = 0 \text{ (since } u + v - w = 0\text{)}$$

We can write the determinant,

$$\begin{vmatrix} 1 & 0 & -m_u u \\ 0 & 1 & -m_v v \\ \frac{1}{m_u} & \frac{1}{m_v} - w \end{vmatrix} = 0$$

because the three equations above are consistent. This determinant may be reduced to the "design determinant" in the following manner:

$$\begin{vmatrix} 1 & 0 & m_u u \\ 0 & 1 & m_v v \\ \frac{1}{m_u} & m_v & w \end{vmatrix} = \begin{vmatrix} 1 & 0 & m_u u \\ 1 & 1 & m_v v \\ \frac{m_u}{m_u} + m_u & m_u w \\ \frac{1}{m_u} + m_u + m_w w \end{vmatrix} = \begin{vmatrix} 1 & 0 & m_u u \\ 1 & 1 & m_v v \\ \frac{1}{m_u} + m_u + m_w w w \end{vmatrix} = \begin{vmatrix} 1 & 0 & m_u u \\ 1 & m_w & m_u + m_w w \end{vmatrix}$$

 $\begin{bmatrix} 0 & m_u u & \mathbf{i} \\ 1 & m_v v & \mathbf{i} \\ \frac{m_u}{m_u + m_v} & \frac{m_u m_v}{m_u + m_v} & \mathbf{u} & \mathbf{i} \end{bmatrix} = 0$   $\leftarrow Design \ Determinant$ 

If the lengths of the u and v scales are 6 in., then

$$m_v = \frac{6}{10 - 2} = \frac{3}{4}$$

$$m_v = \frac{6}{15 - 5} = \frac{3}{5}$$

and

The design determinant becomes:

The chart is constructed from this determinant (Figure 88). It should be noted that the u and v scales are graduated from points 2

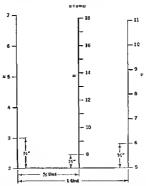


Fig. 88. Chart for the Equation, u + v = w, Constructed by the Method of Determinants.

and 5 respectively. A point on the w scale is obtained from the relation u + v = w.

#### GENERAL REMARKS

1. An equation which can be reduced to the determinant,

$$\begin{vmatrix} 0 & f_1(u) & 1 \\ f_2(v) & f_3(v) & 1 \\ f_4(u) & f_7(u) & 1 \end{vmatrix} = 0$$

will consist of a straight line u scale; and curved scales for v and w.
2. If the determinant is of the form;

2. If the determinant is of the form:

$$\begin{vmatrix} f_1(u) & f_2(u) & 1 \\ f_2(v) & f_4(v) & 1 \\ f_5(w) & f_6(w) & 1 \end{vmatrix} = 0$$

the alignment chart will consist of three curved scales.

3. Design determinants of the form:

$$\begin{vmatrix} 0 & f_1(u) & 1 \\ 1 & f_2(v) & 1 \\ f_3(w) & 0 & 1 \end{vmatrix} = 0$$

will result in a chart having two parallel scales (u and v) and a transverse line for scale w.

The reduction of a given equation to the design determinant form frequently requires ingenuity and resourcefulness on the part of the designer. As one develops facility in manipulating determinants he will evolve short-cuts that will save much time.

In most cases the geometric method will be adequate for the design of alignment charts. However, complicated expressions, especially those which result in charts having two or three curves, may be solved more easily if the equation can be expressed in determinant form directly.

comp in one equivation can be expressed in determinant form directly.

Projective transformations can be handled very nicely if the determinant forms are employed. The interested student is encouraged to consult the bibliography for a selection of books which stress the method of the determinants.

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## INDEX TO APPENDIX ALIGNMENT CHARTS

Alignment charts for determining air, Reynolds modules for, 150 American Standard Bolts, strength of,

bending moments, 146 bolt diameter under tension, 143 breaking load of round wires, 142 Brown-Spearman prophecy formula

for reliability of lengthened test, 172

calculator, production, 163 cathede ray tube, electromagnetic deflection sensitivity, 167

electrostatic deflection sensitivity.

compressible fluids, pitot tube formula for, 165 coefficient of correlation, 171

defication sensitivity of cathode ray tube, electromagnetic, 167 electrostatio, 166

density of fluid in a pitot tube traverse, 164

deviation of a set of scores, 170 dismeter of balts under tension, 143 discharge of water to atmosphere, 159 engine rpm, 139

fittings, resistance to flow of fleids.

flow, power developed from streams.

flow of fluids, resistance of valves and fittings, 151

flow of liquids, in pipes, Reynolds number and friction factor, 153 fluid pressures, shell thickness to with-

stand, 144 fluids, compressible, pitot tube for-

mula for, 165

Alignment charts for determining fluids, density of, in a pitot tube trav-

erse, 164 focal length of thin lenses, 161

friction factor for flow of liquids in pines, 153

impedance, characteristic, of lines. single wire in trough, 168

solid dielectric concentric lines, 169 lengths of V-belts, 145

lenses, focal length, 161

lines, characteristic impedance of, single wire in trough, 168

solid dielectric concentric lines, 169 liquids, viscosity for, 155

pressure drop for turbulent flow, 157 load on round wires, 142

moments, bending, 145 pipes, pressure drop in, 149

Reynolds number and friction factor, 163

pitot tube, formula for compressible fluids, 165

traverse, density of fluid, 164 power, developed from stream flow,

required to pump water, 147 pressure, shell thickness for, 144 pressure drop, in liquid line (turbulent

flow), 157 in pipe line, 149

production calculator, 163 prophecy formula for reliability of lengthened tests, 172

resistance of valves and fittings to flow of fluids, 151

Reynolds modulus for air, 150 Reynolds number for flow of liquids in pipes, 153

Altenment charts for determining rom, engine, 139 shell thickness for fluid pressures, 144 Spearman-Brown prophery formula for reliability of lengthened test,

standard deviation of a set of scores, 170

stream flow, power developed from,

strength, of American Standard bolts, 141 tersional, of shafts, 140

tension, bolt diameters under, 143 thickness, shell, for fluid pressures, 144 Alterment charts for determining termonal strength of shaits, 140 tube, putot, formula for compressible

fluids, 165 traverse, density of fluid, 164 tubing, weight of, 162

turbulent flow, pressure drop in liquid lines, 157 valves, resistance to flow of fluids, 151 V-belt lengths, 145 viscouty of Liquids, 155 water, discharged to atmosphere, 159 power required to pump, 147

weight of tubing, 162 wires, breaking load, 142

These are examples of alignment charts which may prove useful in the fields of engineering, production, business, and statistics.

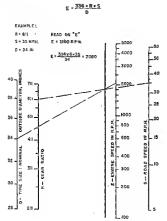


Fig. 1A. Alignment Chart to Determine Engine R.P.M.

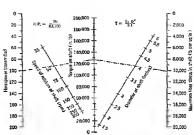


Fig. 2A. Shafts for Tormonal Strength. (Courtesy Product Engineering.)

For calculating the horsepower that can be transmitted by a given shall at a given speed, the following equation can be used.

$$\Pi_{i}^{p} = \frac{z_{i}h^{2}N}{2\pi i}$$
(1)

The equation may be divided into two parts.

and

$$S_s = \frac{16T}{r^2}$$
 (2)

 $HP = \frac{TN}{22.000}$ 

$$Hb = \frac{2X_{100}}{2X_{2}}$$
(3)

 $\mathcal{E}_r = \max \text{ ebracies etems},$ 

Managelation of the chart is Husbated by the deeb love. Thus, if 100 kp m to be transmitted at a speed of 50 ym. the across in the outer fibers of a 4-m, design, solid shaft will be distribly in excess of 10,000 lb per op m.

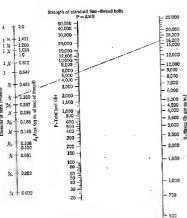
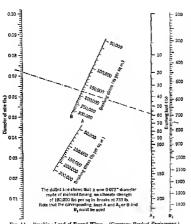


Fig. 3A. Strength of American Standard Bolts. (Courtesy Product Engineering.)



Breaking Load of Round Wires. (Courtesy Product Engineering)

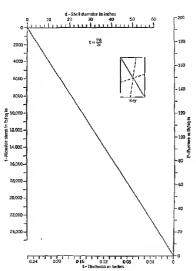


Fig. 6A. Remired Shell Thickness for Various Fluid Pressures

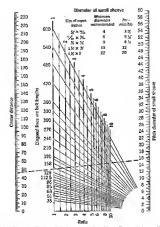


Fig. 7A. Chart for Finding Belt Lengths, V-Belt Short-Center Drives. (Courtesy Product Engineering. Information courtesy of Alks-Chalmers Manufacturing Co.)

Given pixth diacester of the small shows, conter distance, and speed ratios to find hearth of V-belt, place recipilated on the shoren points of small shower dissarders which and conter distance Guth and place of the content distance Guth and depict of the content of the conte

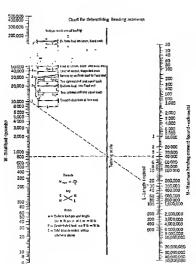
Excitence Dotted line draws between points representing small sheave diameter of 25,65 in, and center distance 46 in intersects ratio line 2.6 at diagonal line for 180 in, belt length.

The V-belt drive consists of a driving and driven shows, grooved for a melliplicity of belts of traprodal connection. Peers in transmitted by the wedging contact between the letter and groots At maximum load, repeated tests show an efficiency of UP per cast and a coefficient of friedm of 1.6. Whill drive operate, therefore, with comparaisvely result toution on the stack side, without drapping and with SiM corecy. In figuring looks, kis transfer, side to take 1.5 times the tourset to get the total

belt pull. Manufacturer's estings must be exemited for selection of number and size of beits for river land conditions.

A Votet drive vill meally be well proportioned when the enter distance results or is slightly greater than the tope relever distance. On small ratio the deserves may be operation of school's specified that the theory of the conditions of the condition of the

In the accompanying chart, the cheave districtors are the pitch diameters, measured at the midpoint of the traperoidal accion of the belt when resting in the groove.



Fro SA. Chart for Determining Bending Momenty (Courtesy Product Engineering.)

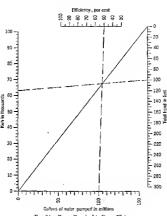
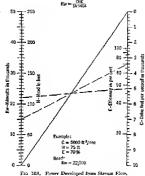


Fig. 9A. Power Required to Pump Water.



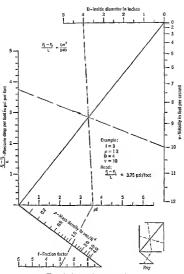
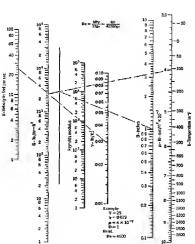


Fig. 11A. Pressure Drop in Pipe Line.



F10. 12A. Reynolds Modulus for Air.

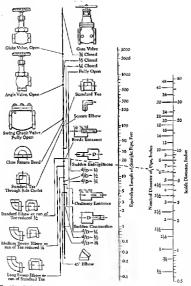


Fig. 18A Resistance of Valves and Fittings to Flow of Fluids. (Courtesy Crans Co.)



The chart on the page below solves the formula:

Reynolds Numbers and Friedon Factor for the Flow of Liquids in Phys. (Courtesy Grans Co.) Decembed from the Rate of Fron, Viscosity, Pres Disnetes, and the Dunity or Specific Gravity) Fig. 14A.



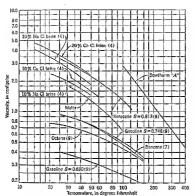


Fig. 15A. Viscosity of Various Liquids. (Courtesy Crane Co.)

It is good practice to assume that flow in pipes is turbulent for all Roynolds numbers greater than 1200. The chart on the pape below is a solution of the Saminie formula for introduct flow.



Fig. 164. Pressure Drop in Liquid Lines (Turbulent Flow). (Courtesy Crans Co.) (Determined from Rate of Flow, Frietien Factor, Fips Dismoter, and Density.)

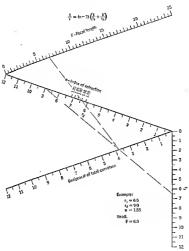
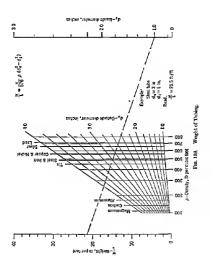


Fig. 18A. Focal Length of Thin Lenses.



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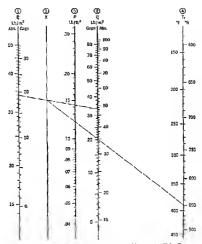


Fig. 21A. Nomegram for Solving for Density of Fluid in a Pitot Tube Traverse, (Courtesy Consolidated Vulter Arcraft Corp.)

$$\rho = \frac{P_S}{R} \times \frac{1}{T_T} \times \left(\frac{P_T}{P_S}\right)^{\frac{K-1}{K}}, \text{lb/fs}$$

$$K = 14 \text{ (for alr)}$$

where R = \$3.3 ft-lb/"F/lb of aur

Tr = stagnation temp, \*A

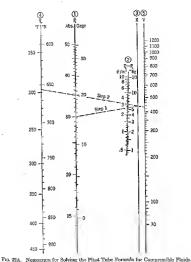
Pr = stagnation pres

Associate wree

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Example:  $O(rec)^*P_S = 34.0 \text{ Byta}^2 \text{ sto}, P_T = 48.0 \text{ Byta}^2 \text{ sto}, T_T = 890^{\circ}R$ Connect 34.0 on scale 1 to 48.0 on scale 2 and thus locate point X on scale 3. Connect point X with \$50 on scale 5 and roth sawrer, p = 0.195, on scale 3.



(Courtesy Consolidated Vulter Aircraft Corp.)

$$V = \sqrt{2\rho I G_P T_T} \left[ 1 - \left( \frac{P_S}{P_T} \right)^{K-J} \right]$$
 ft/see  
where  $\rho = 32.17$  ft/see $^J$ ,  $J = 776$  ft-4b/BTU,  $K = 1.4$ ,  $G_P = 0.24$  BTU/FP/lb air

 $T_T = \text{stagnation temp}_n$  R  $P_T = \text{stagnation pres.}$  [b/in, 2 abs., or similar units]

PS = static pres.  $\stackrel{1}{\sim} 19^{1}\text{cs}^{-1}$  abs. or similar units Excupc. Given:  $P_S = 20.9 \text{ By/m}^{-1}$  abs.,  $P_T = P_S = 2.6 \text{ By/m}^{-1}$ ,  $T_T = 196^{\circ}F$ . Connect 30.0 on scale 1 to 2.0 on scale 2 and not point X on scale 3. Connect this point with 195 on scale 4 and read enswer on scale 5, V = 420 ( $I_{VPC}$  on.

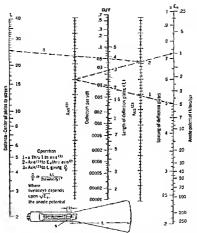


Fig. 23A. Deficetion Sensitivity of Cathodo Ray Tubo—Electrostatic Defication.
(Courtesy Federal Telephone and Radio Corp.)

The electrostate deflection sensitivity of a cathoda say tube, for a given annia potential  $(E_A)$ , depends on spectra; (3) and length (9) of deflection plates, and their datases (3) to the acress. A line from (1) and (2) scales is exceeded to sat (3). From latter laberaction, a second low is derive to  $(E_A)$  scale intersecting a ran (9). From the posst, a blief lenk is drawn through (12) and extended to letter of the posst of the posst, a blief lenk is drawn through (12) and extended to the test of the posst of the p

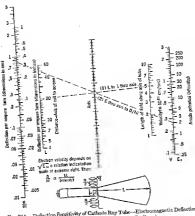
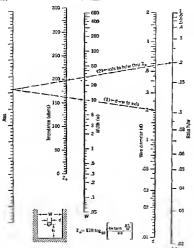


Fig. 24A. Deflection Sensitivity of Cathode Ray Tube—Electromagnetic Deflection. (Courtesy Federal Telephone and Radio Corp.)

The electromagnetic deflection sensitivity of a enthode ray tube cannot be determined with accuracy owing to difficulty of computing intensity and discontinue of magnetic field. With no flux letter and our chart, as indicated. The age of the superminants deflection can be determined from chart, as indicated. The defection per ampere turn scales (for unit when dimendenal systems are in centimeters and in inches) are at left. The scale at right shows election velocity resulting from a given anode potential.



Frg. 25A. Characteristic Impedance of Lines—Single Wire in Trough. (Courtesy Federal Telephone and Radio Corp.)

Start with d and W values and extend hos to any. From lattice point, a limit to A/w scale will interact  $\mathbb{Z}_2$  and at resulting impedance value. Engineering accounts when w/d > b and d/d > 1.5 Relations are only appreciated beyond these values. Assumes believed to the day and protect conductors. Roles of trengt around w/d > 0 to grade of the finite w/d > 0 and w/d > 0. For other distortion multiply w/d > 0 in  $1/\sqrt{2}$  where w/d > 0 is distortion and w/d > 0.

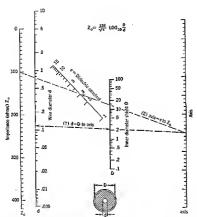


Fig. 28A. Characteristic Impedance of Lines—Concentric Line, Solid Dielectric. (Countesy Federal Telephone and Radio Corp.)

This chart gives theoretically eract values for any scale of discensions, if Ionibus disloctric is assumed (filling completely the space between conductors), and perfect conductors. Line from d and D under catcade to the axis. Proc all the point a line through B scale will indusped S = rails at resulting value.

Example: d = .12 cm, D = 2.1 cm, E = 3.0,  $Z_0 = 102$  ohms.

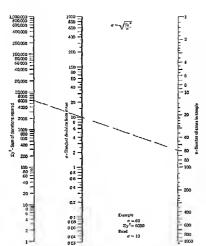


Fig. 27A. Standard Deviation of a Set of Scores.

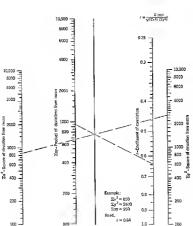


Fig. 28A. Coefficient of Correlation.

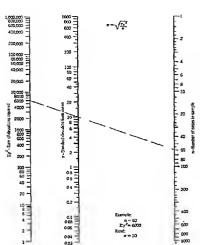


Fig. 27A. Standard Deviation of a Set of Scores.

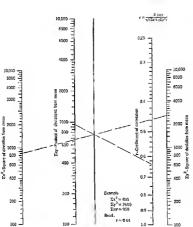
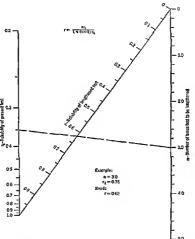


Fig. 28A. Coefficient of Correlation,



F10. 29A. Spearman-Brown Prophecy Formula for Rehability of Lengthened Test.

Actual modulus, 14 Adjacent scales, 19-21 circumference of a circle, 20 conversion of inches to continueters, 19 for equations of the form  $f_1(u) = f_2(u)$ ,

19-21 for solution of the formula.

> $C = \tau D, 20$  $U = \sin V$ , 21  $V = \frac{4}{3}\pi^2$ , 21 2.54I = C.19

value of the sine function, 21 volume of a sphere, 21 Alignment charts, 10, 25-75, 99-103,

122-135 (see also Z charts) alternate methods, 61, 106-107 bending moments, 122-123 combined with Cartesian co-ordinate chart. 10. 11

with proportional charts, 109-110 construction, 27, 44, 60, 100-101 flow through an orifice, 70–75 for equations of the form,

 $f_1(u) = f_2(v) \cdot f_3(w), 44-53, 116$  $f_1(u) + f_2(v) = f_3(w)$ , 25-35, 116  $f_1(u) + f_2(v) = \frac{f_1(u)}{f_2(v)}, 54-58, 117$  $f_1(v) + f_2(v) + f_2(w) \cdot \cdot \cdot = f_4(v), 68-$ 

75, 119  $f_1(u) + f_2(v) \cdot f_3(w) = f_4(w), 99-103$  $f_1(u) + f_2(v) \cdot f_3(w) = f_4(a), 108, 121$  $f_1(u) \cdot f_2(v) + f_3(w) \cdot f_4(q) = f_6(q), 107$ 

 $\frac{1}{f_1(u)} + \frac{1}{f_2(v)} = \frac{1}{f_2(w)}$ , 59-67, 118

 $\frac{1}{f_1(u)} + \frac{f_4(w)}{f_2(v)} = \frac{1}{f_3(w)}$ , 108–109

Alignment charts, for equations of the form-

 $\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_2(w)}{f_4(v)}, 104-107$ 

lens formula, 62-63 moment of inertia of a rectangle, 32-34

negative values, 36 positive values, 36 practical chort-cuts, 122-125 resistances in parallel, 64-67

acction modulus for tubes and bars, 124-125

solutions of the formula.  $I = \frac{1}{12}bd^3$ , 32–34  $M = \frac{1}{8}wt^2$ , 122–123

 $R = 19.64Gd^3\sqrt{L}$ , 70-75  $\frac{1}{r_1} + \frac{1}{r_2} = \frac{1}{r_3}$ , 64-67

 $S = 0.0982 \left( \frac{D^4 - d^4}{T_1} \right)$ , 124–125 u + v = w, 28, 32, 127-131, 183-134 u - v = 10, 35-36

u + 2v + 3w = 4t, 68-69 $u + vw = w^2$ , 181-132  $\frac{1}{n} + \frac{1}{n} = \frac{1}{6}$ , 62-63

 $w^2 + pw + q = 0$ , 101-102use of determinants, 126-135

Z chart (see Z chart) Alternate methods, for alignment charts,

61, 106-107 for proportional charts, 96-97, 120 for Z charts, 106-107 Appendix, 139-172 Appendix index, 137-138

Design determinant, 125 Design of net charts, 111-114

Effective modulus, 14

Determinants, 10, 126-135

Engine, horsepower, 51-53

Engine, rom, S.

negative values, 16

17

non-adjacent scales, 22-24 suggestions for drawing scales, 16-

suggestions for graphic precision, 17

Dat chart, I	rangime, gram, 8
Bars and tubes, section modulus of, 124-	Equations (see also Solutions of formula
125	of the form
Bending moments, 122-123	
Bibliography, 136	$f_1(u) = f_2(v), 19$
	$f_1(u) = f_2(v) \cdot f_2(w), 44-53, 116$
Buoy, valume of, 92-94	$f_1(u) + f_2(v) = f_3(u), 25-35, 116$
Cartesian po-ordinate charts, 4-11	$f_1(u) + f_2(v) = \frac{f_1(u)}{f_2(v)}, 54-58, 117$
combination of, 3, 5-9	
for equation of the form $f_1(u)$ +	fo(so)
$f_2(v) + f_3(w) = f_4(q), 3$	$f_1(u) + f_2(v) = \frac{f_2(u)}{f_4(v)}$ , 90–98, 120
graph to determine engine rpm, 7-8	
graphical evaluation of heat storage	$f_1(u) + f_2(v) + f_3(w) = f_4(q), 3$
	$f_1(u) + f_2(v) + f_3(v) \cdot \cdot \cdot = f_4(a), 68$
and transfer characteristics, 7, 9	75, 119
solution of the formula	$f_1(\omega) + f_2(v) f_2(\omega) = f_4(\omega), 90-103$
u + v + w = q, 5	$f_1(u) + f_2(v) f_3(w) = f_4(q), 108, 121$
up ⇔ u, 5–6	$f_1(u) + f_2(v) + f_3(u) + f_4(q) = f_6(q), 107$
upu ≈ σ. 6–7	
upu = q, 0−1	$f_1(u) \ f_2(t) \ f_3(w) = f_4(q) \cdot f_1(r), \ 109-110$
combination with alignment chart, 10-	$f_1(u) \ f_2(v) \ f_4(u) = f_4(q) \ f_6(r) \ f_6(s), 11$
11	1 1 1 2 22 22 22
nomograph for determining the num-	$\frac{1}{f_1(w)} + \frac{1}{f_2(v)} = \frac{1}{f_2(w)}$ , 59–67, 118
ber of seconds of green light for	1 160
traffic signals, 11	$\frac{1}{f_1(\omega)} + \frac{f_4(\omega)}{f_7(\omega)} = \frac{1}{f_2(\omega)}$ , 109–109
solution of the formula $u + v = T$ , 4	
Cartesian co-ordinate system, 2-11	$\frac{f_1(u)}{f_2(v)} = \frac{f_3(w)}{f_4(q)}$ , 70–89, 119
	$\frac{2}{6(m)} = \frac{2}{6(m)}$ , 70-89, 119
family of parallel lines, 3	12(v) 14(q)
logarithmic scales, 5, 6, 7	$\frac{f_1(u) + f_2(v)}{f_1(u) - f_2(v)} = \frac{f_2(u)}{f_2(v)}, 104-107$
pennil of lines, 6	$f_1(u) = f_2(v)$ $f_4(v)$
Circumference of a circle, 20	
Column formula, 55-57	Evaporation formula, 50-82
Combination charts, alignment chart and	
Cartesian co-ordinate chart, 10, 11	Family of parallel lines, 3
alignment chart (Z chart) and propor-	Flow through an ordice, 70-75
tional chart, 109-110	Formula (see Solutions of the formula)
Cartesian co-orduste charts, 3, 5	Functional scales, 12-24
proportional charte, 110	adjacent scales, 19-21
Construction of abgament charts, 27	for the function.
44, 60, 100-101	$f(u) = u^2, 12-13$
proportional chart, 91-92	f(u)=u+2,14
Z chart, 44	$f(u) = \sqrt{u}$ , 15
Conversion of muches to centimeters, 19	1
Cylinder, volume of, 46-49	$f(u) = \frac{1}{u^2}, 15$
	-
Design determinant, 125	f(u) ≈ log u, 16

Gordon column formula, 55-57 Graphical scale, 12

Heat storage and transfer obstactoristics,

Initial point, 12, 15 Introduction, 1

Logarithmic scales, 5, 6, 7, 32, 70, 76 Lens formula, 62-63

Meyer's evaporation formula, 80-82 Modulus, actual, 14 effective, 14

scale, 14 Moment of inertia of a rectangle, 32-34

Negative values, alignment charts, 26, 43 functional scale, 16 Z chart, 43 Net charts, 111-114

solution of the formula S = Vet + 4at2. 111-114 Nomograph to determine the number of

seconds of green light for traffic signals, 11 Non-adjacent scales, for equations of the form  $f_1(u) = f_2(v)$ , 22-24

solution of the formula 2.54I = C, 23,

Orifice, rate of flow through, 70-75

Parallel resistances, 64-67 Pencil of lines, 6 Pie chart, 1

Pipe thickness for internal pressures, 78-

Positive values, alignment chart, 36, 43 Z chart, 43 Practical short-cuts, 122-125

Profile chart, 1 Proportional charts, 76-98 alternate forms, 96-97, 120 combination of, 110

combined with alignment (Z chart) chart, 199-110

Proportional charts. construction, 91-92 for equations of the form,

 $f_1(u) + f_2(u) = \frac{f_3(u)}{f_1(u)}, 90-98, 120$ 

 $f_1(u) \cdot f_2(v) \cdot f_3(w) = f_4(q) \cdot f_6(r), 109$ 

 $f_1(u) \cdot f_2(v) \cdot f_3(w) = f_4(q) \cdot f_6(r) \cdot f_6(s),$ 

 $\frac{f_1(u)}{f_2(e)} = \frac{f_1(w)}{f_4(e)}$ , 76-89, 119

Meyer's evaporation formula, 80-82 solution of the formula,

 $E = 15(V - v) \left(1 + \frac{w}{10}\right)$ , 80–82

 $t = \frac{Pd}{2c}$ , 78–79  $u^2 - v^2 = \frac{w}{4\pi}$ , 04-97

 $V = \frac{\pi \hbar}{3} \left( \frac{5}{4} D^2 + d^2 \right), 92-94$ thickness of a pipe to withstand inter-

nal pressures, 78-79 volume of a buoy, 92-94

Rectangle, moment of inertia, 32-34 Reference point, 12, 15 Resistances in parallel, 64-67

Scale, equation, 5, 6, 7, 32, 70, 76 logarithmic, 13 modulus, 13

Simplified method for Z charts, 50, 51~

Sine function, value, 21 Solution of the formula,

 $B = \frac{d^2n}{n\pi}$ , 51–53

 $C = \pi D, 20$ 

 $\dot{E} = 15(V - v) \left(1 + \frac{tv}{10}\right)$ , 80-82

 $f = \frac{20,000}{1 + \frac{144L^2}{0.000}}, 55-57$ 

176 INDEX

Solution of the formula. I = vald. 32-34  $M = \frac{1}{2}ml^2$ , 122-123

 $R = 19.64 \alpha P_3 / h$ , 70–75

 $\frac{1}{r_1} + \frac{1}{r_2} = \frac{1}{r_1}$ , 64-67

 $S = 0.0982 \left( \frac{D^4 - d^4}{D} \right), 124-125$ S = Vet + 1et. 111-114

 $t = \frac{Pd}{2t}, 78-79$ u = sin. p. 21 u + v = w, 28-82, 127-131, 183-134

4+++==0.5 u + 2r + 3w - 44,68-69 $u = v = \omega_1 25-30$ 

 $u + 2 = v^2u$ , 45-46  $u + v = w^{1}$ , 131-132 20 € 25, 5-6

uvv = a, b-7 $w^2 + pw + a = 0.101-102$ 

 $u^2 - v^2 = \frac{w}{4\pi}$ , 94-97 1+1-1, 62-63

 $V = \frac{\pi h}{a} \left( \frac{5}{7} D^2 + d^2 \right), 92-94$ 

 $V = \frac{4}{3}\pi^2$ , 21 2.54 $\tilde{t} = C$ . 19

Sphere, volume of, 21

Thickness of pipe for internal pressure. 78-79

Tubes and bars, section modulus, 124-

Volume of, buoy, 92-94 cylinder, 46-49 sphere, 21

Z charts, 43-58 (see also Alienment. charts)

alternate form, 106-107 combined with proportional chart, 109. 110

construction, 41 for equations of the form.

 $f_1(w) = f_2(v) f_1(w), 44-53, 116$  $f_1(u) + f_2(v) = \frac{f_1(u)}{f_1(u)}$ , 54-58, 117

 $f_1(\omega) + f_2(v) f_3(\omega) = f_4(o), 108$  $f_1(u) f_2(v) + f_2(u) f_4(v) = f_3(v)$ , 107  $f_1(u) f_2(v) f_3(w) = f_4(q) f_5(r), 109-$ 110  $\frac{f_1(u) + f_2(v)}{G(u) - G(v)} = \frac{f_2(w)}{G(v)}$ , 104–107

Gordon column formula, 55-57 horsepower developed by automobile engino, 51-53 simplified action, 50, 51-58

solution of the formula,  $B = \frac{d^2n}{25}, 41-53$ 

 $f = \frac{20,000}{1 + \frac{144L^2}{2000}}, 55-57$  $u + 2 = v^2 v$ , 45-46

V = = 174 , 46-49

volume of a cylinder, 46-49 Zero point, 12, 15